

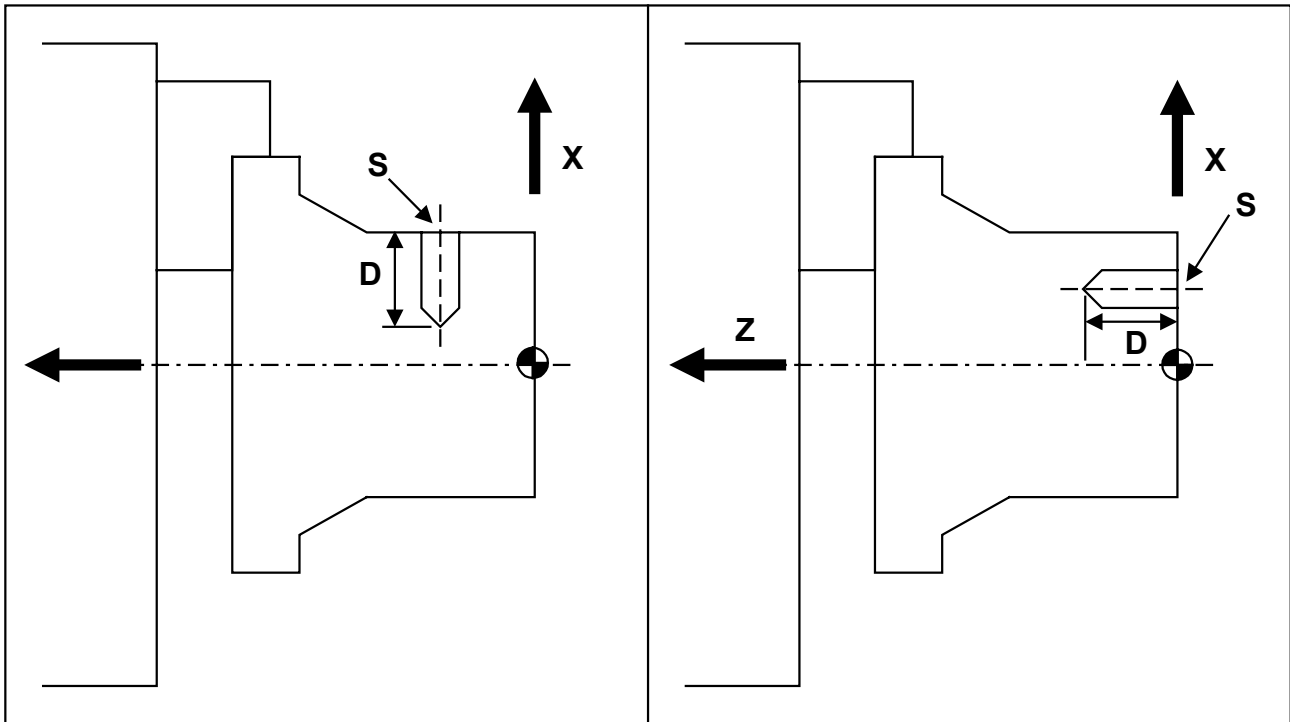


MILLING UNIT INFORMATION



MDR OUT

MDR FCE



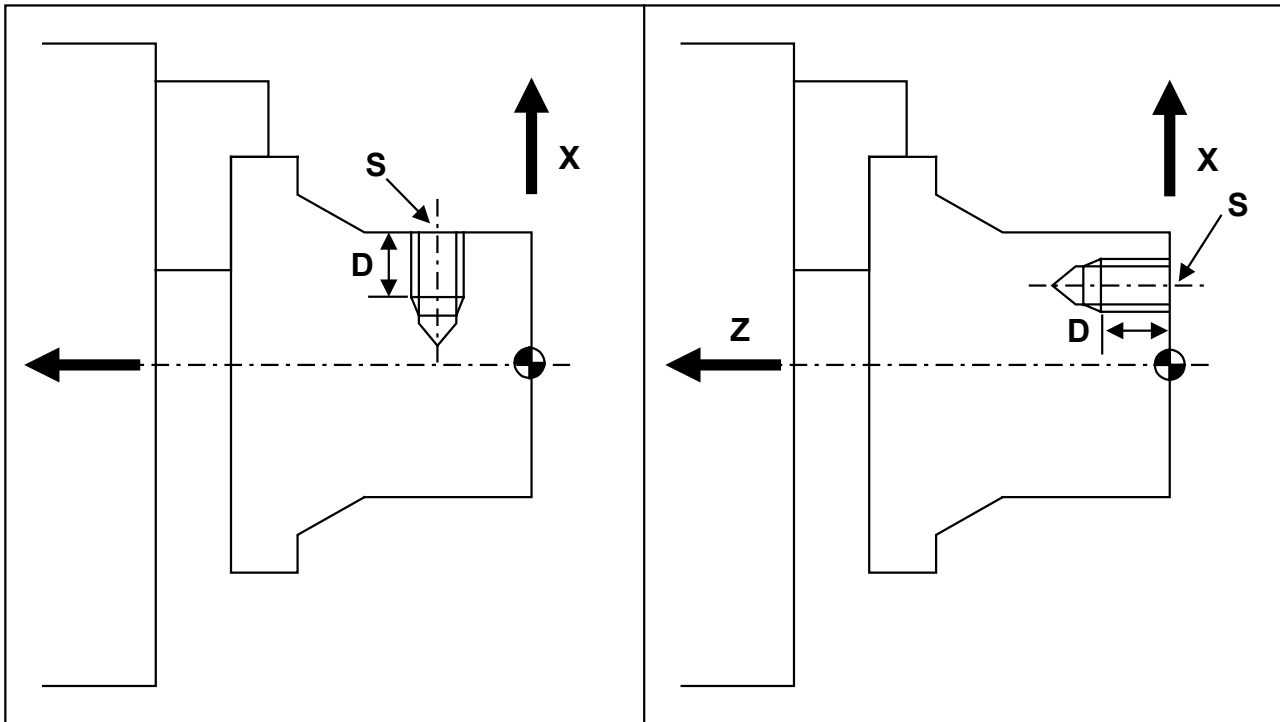
POINTS TO NOTE

1. The control automatically positions the tool clear of the material by a clearance amount set in parameters.
2. Positions to the right of Z zero are defined as negative z co-ordinates.
3. When using the "BOTTOMED" drill cycles, the programmed depth is based on the depth of the drill point in the material.
4. When using the "THROUGH" drill cycles, the programmed depth is based on the full diameter drilling depth - material length. The control automatically allows for the extra drilling depth by referring to the TOOL DATA page (for the drilling point allowance), and to a parameter, for the through clearance.
5. Feedrates at the start and finish of the drilling can be altered by parameters.
6. Cycle Types: #0 = peck,feed retract. #1 = peck, chip clear.
#2 = peck,chipbreak. #3 = ream. #4 = #1 & #2 combination.

NB. S = starting point. D = depth.

MTP OUT

MTP FCE



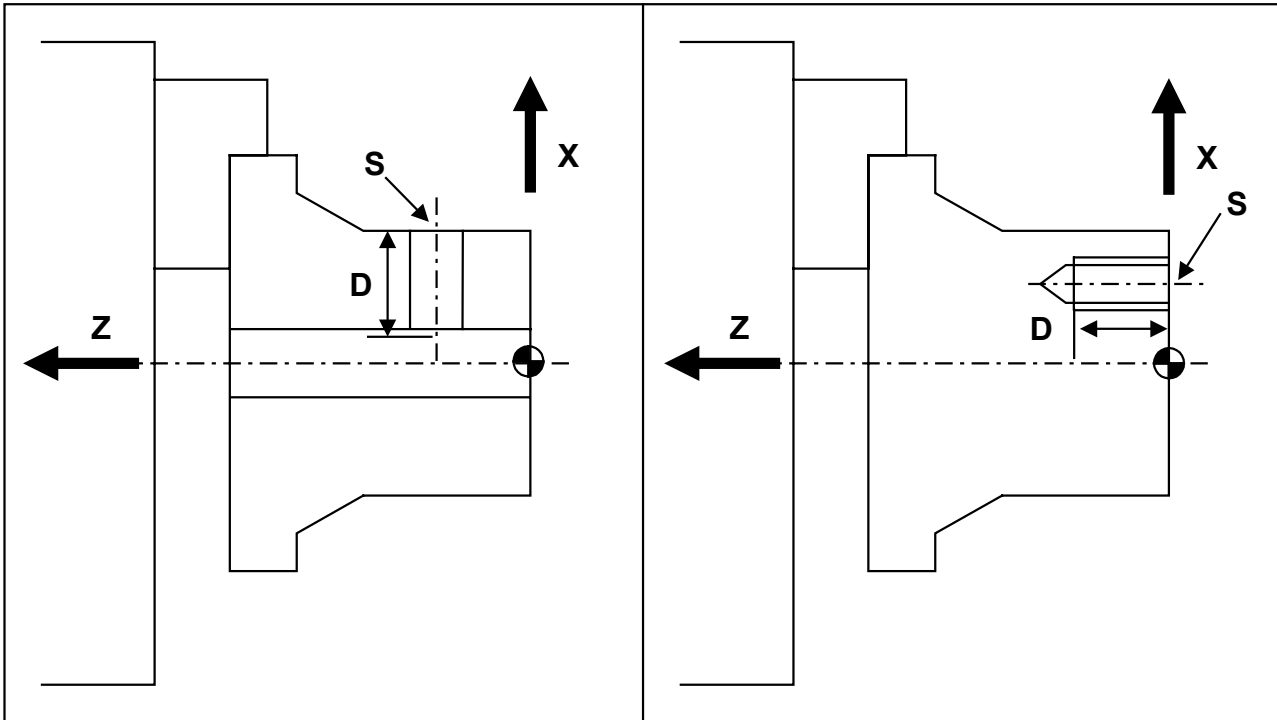
POINTS TO NOTE

1. The control automatically positions the tool clear of the material by a clearance amount set in a parameter.
2. Positions to the right of Z zero are defined as negative Z co- ordinates.
3. The actual depth in the program is based on the full thread length.
4. The control automaticlly allows for the taper lead section of the tap by a parameter setting.
5. The control automatically allows for the taper elongation when retracting, by a parameter setting.

NB. S = starting point. D = depth.

BOR OUT

BOR FCE

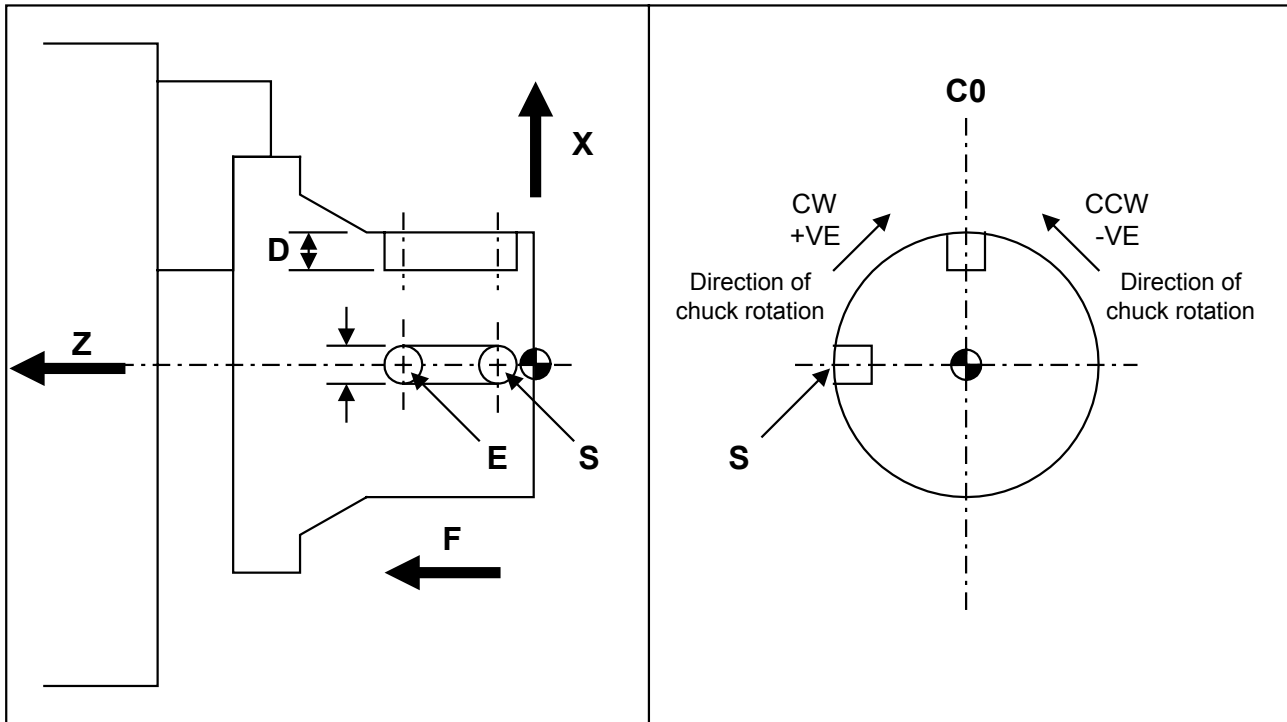


POINTS TO NOTE

1. The control automatically positions the tool clear of the material by a clearance amount set in a parameter.
2. Positions to the right of the Z zero are defined as negative z co-ordinates.
3. The actual depth in the program is based on the tool boring depth. Therefore, allowances must be included if the tool is boring through.
4. For INTEGREGX type machines, spindle orientation, and tool tip relief are possible, but only when the tool is mounted horizontally.
5. Cycle types: #0 = Feed in, Feed out.
 #1 = Feed in, Orient mill spindle (Integrex type m/c only), Rapid out.
 #2 = Feed in, Orient mill spindle, Tool retract, (Integrex type m/c only), Rapid out.

N.B S = Starting point, D = Depth.

MGV OUT

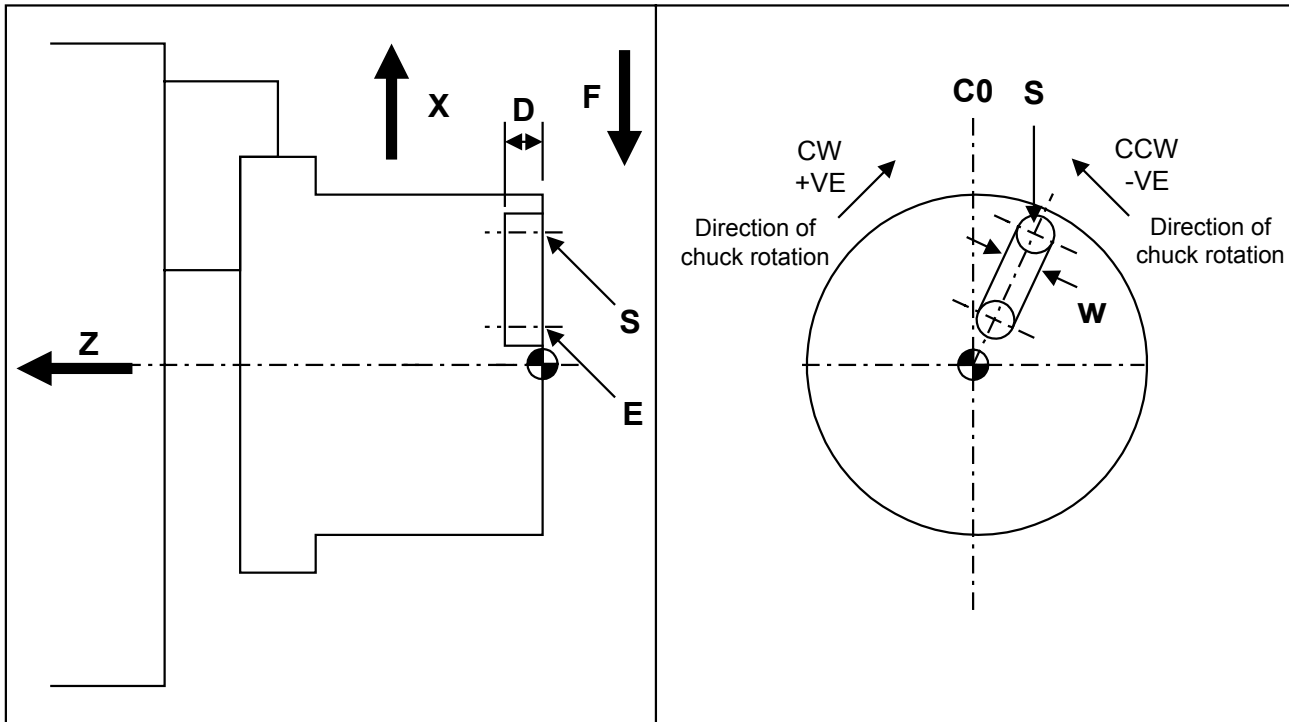


POINTS TO NOTE

1. The control automatically positions the tool clear of the material by clearance amounts set in parameters.
 2. Positions to the right of the Z zero, are defined as negative Z co-ordinates.
 3. The center line detail of the MGV feature must be a straight line parallel to the Z axis, and pass through the component center line.(Non Y axis machines.)
 4. The finish tool diameter must be equal to the required slot width.
(Non Y axis machines.)
 5. While cutting, the C axis is clamped.
 6. Cutting patterns: #0 = Uni-directional. #1 = Bi-directional.
#2 = CW cut.* #3 = CCW cut.*
- (*) For Y axis machines only, and for these cycles, Wall Fin Allowance = Axial Fin Allowance.

N.B S=Start point, E=Final point, D=Depth, W=Width, F=Main feed direction.
(Start pt, Final pt and Main feed directions can be reversed.)

MGV FCE

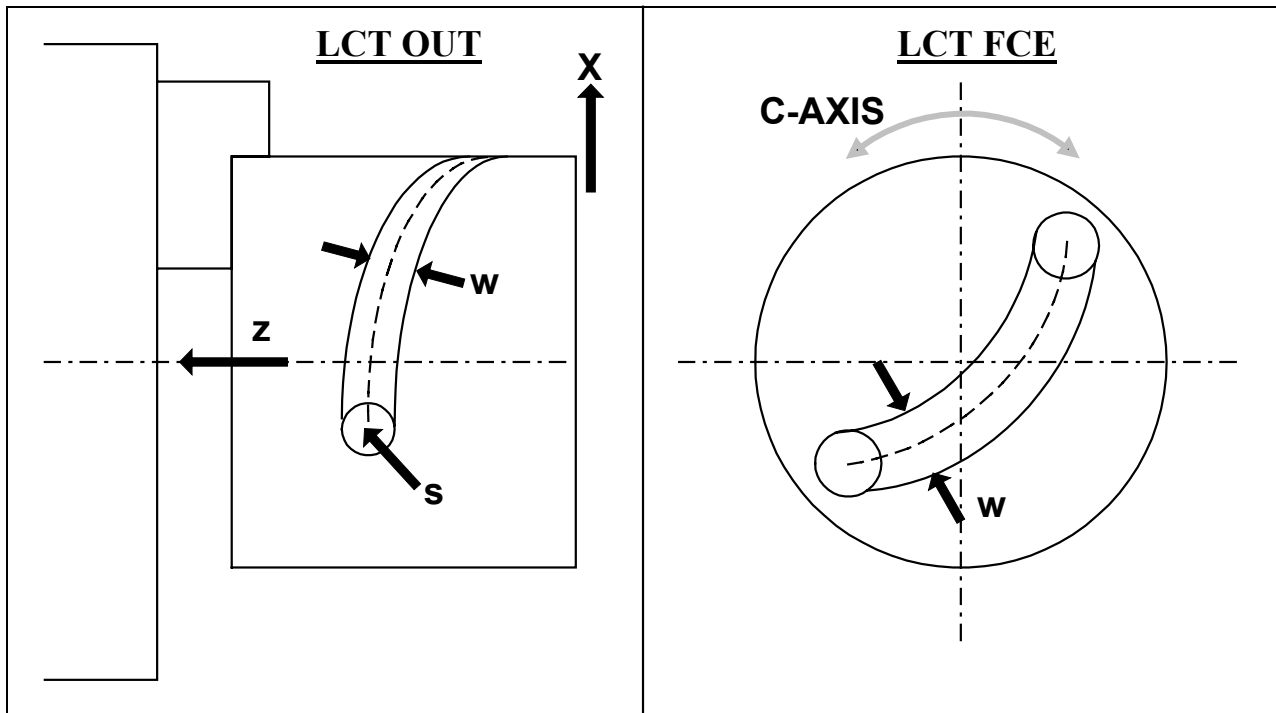


POINTS TO NOTE

1. The control automatically positions the tool clear of the material by clearance amounts set in parameters.
2. Positions to the right of the Z zero are defined as negative Z co-ordinates.
3. The **centre line** detail of the MGV feature, must be a straight line on the face of the component, and must pass through the component centre.
4. The finish tool diameter must be equal to the required slot width.
5. While cutting, the C axis is clamped.
6. Cutting patterns: #0 = Uni-directional. #1 = Bi-directional.

N.B S = Start point. E = Final point. D = Depth. W = Width. F = Main feed direction.

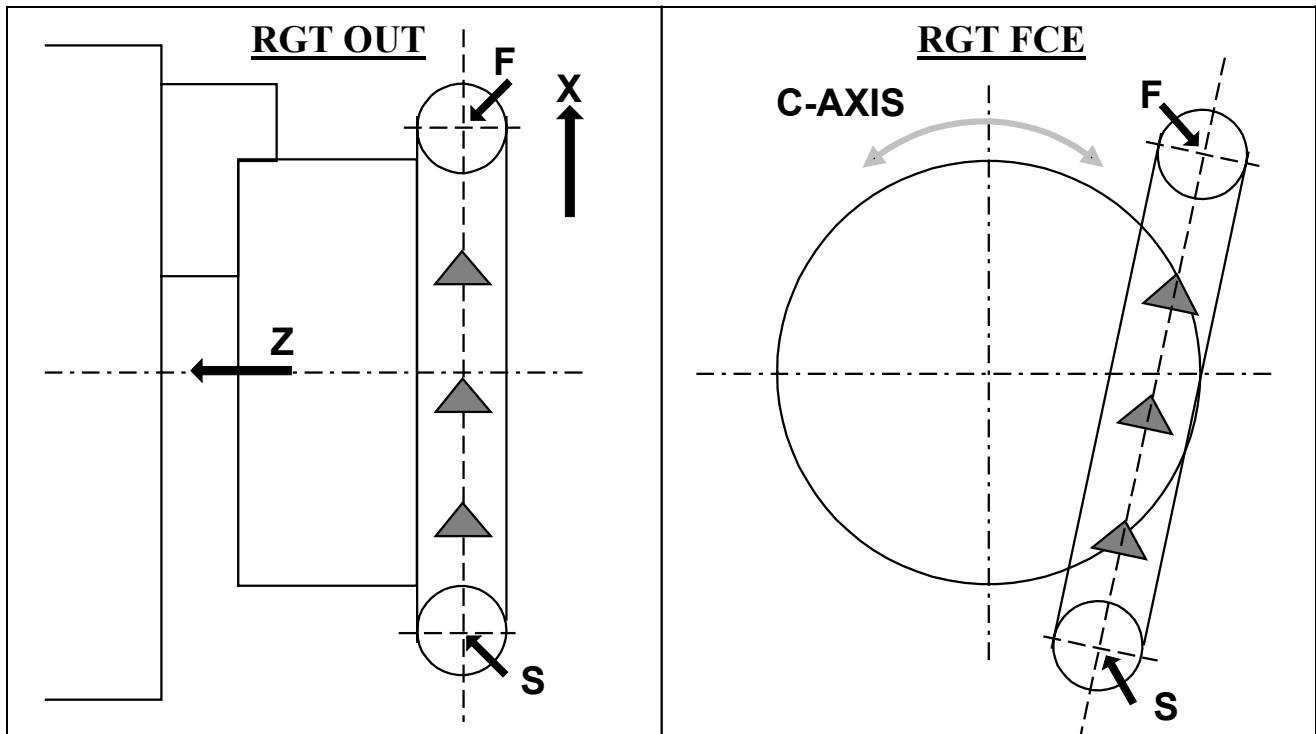
(Start pt, Final pt and Main feed direction, can be reversed).



POINTS TO NOTE:

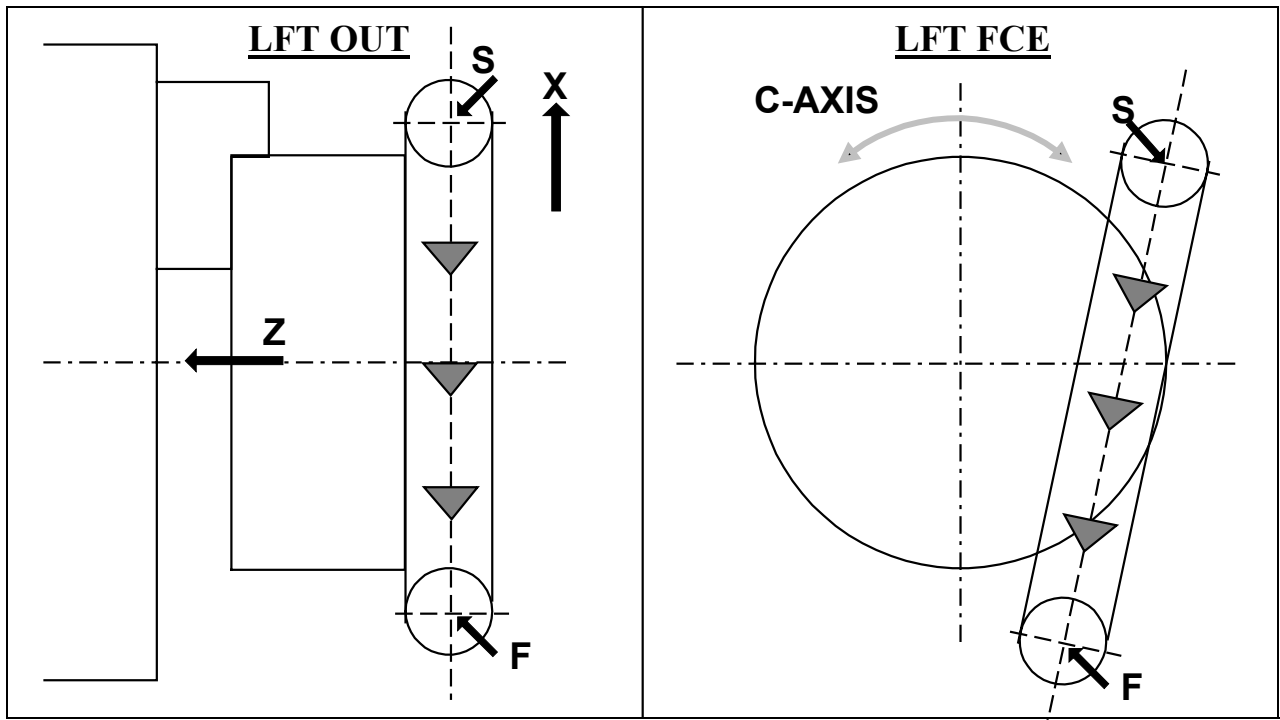
1. The control automatically positions the tool clear of the material by clearance amounts set in parameters.
2. Positions to the right of Z zero are defined as negative Z co-ordinates.
3. This process positions the cutter centre ON the line defined.
4. While machining using a LCT OUT unit, once a desired cut radius has been set the machine uses Z-Axis and C-Axis (or Y-Axis, with option) to produce the profile.
5. While machining using a LCT FCE unit, once a desired cut radius has been set the machine uses X-Axis and C-Axis (or Y-Axis, with option) to produce the profile.
6. Initial positioning of the cutter must be specified by START POINT before profiling of the feature begins.

N.B. W= width of groove



POINTS TO NOTE:

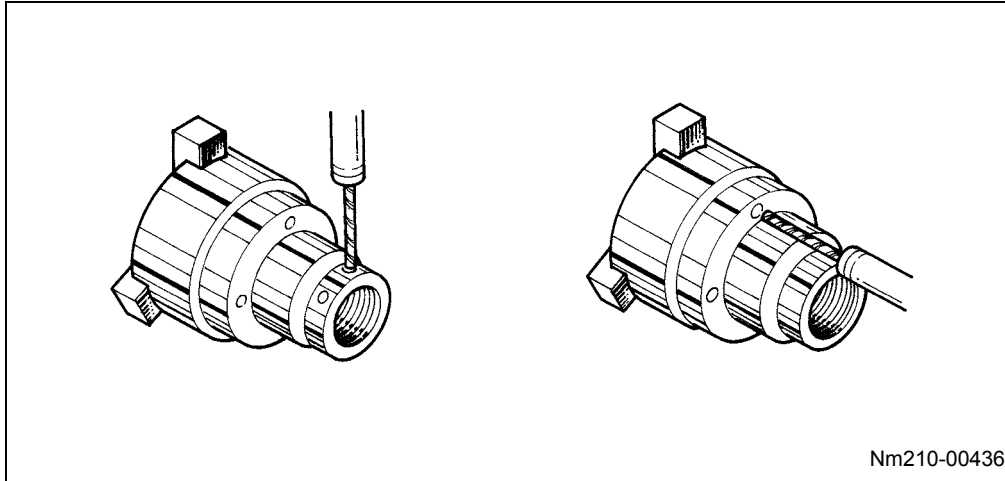
1. The control automatically positions the tool clear of the material by clearance amount set in parameters.
2. Positions to the right of Z zero are defined as negative Z co-ordinates.
3. This process positions the cutter to the right-hand side of the line defined.
4. While machining using a RGT OUT unit, once a desired cut radius has been set the machine uses Z-Axis and C-Axis (or Y-axis, with option) to produce the profile.
5. While machining using a RGT FCE unit, once a final point in Z-Axis has been set the machine uses X-Axis and C-Axis (or Y-axis, with option) to produce the profile.
6. Initial positioning of the cutter must be specified by START POINT before profiling of the feature begins.



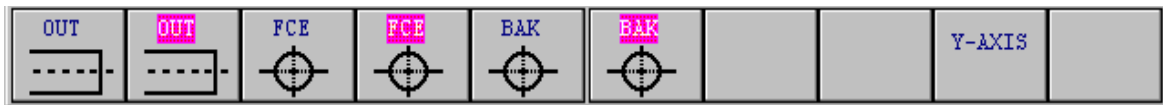
POINTS TO NOTE:

1. The control automatically positions the tool clear of the material by clearance amounts set in parameters
2. Positions to the right of the Z zero are defined as negative Z co-ordinates.
3. This process positions the cutter to the left-hand side of the line defined.
4. While machining using a LFT OUT unit, once a desired cut radius has been set the machine uses Z-Axis and C-Axis (or Y-Axis, with option) to produce the profile.
5. While machining using a LFT FCE unit, once a desired cut radius has been set the machine uses X-Axis and C-Axis (or Y-Axis, with option) to produce the profile.
6. Initial positioning of the cutter must be specified by START POINT before profiling of the feature begins.

NOTES RELATING TO MDR/MTP UNIT



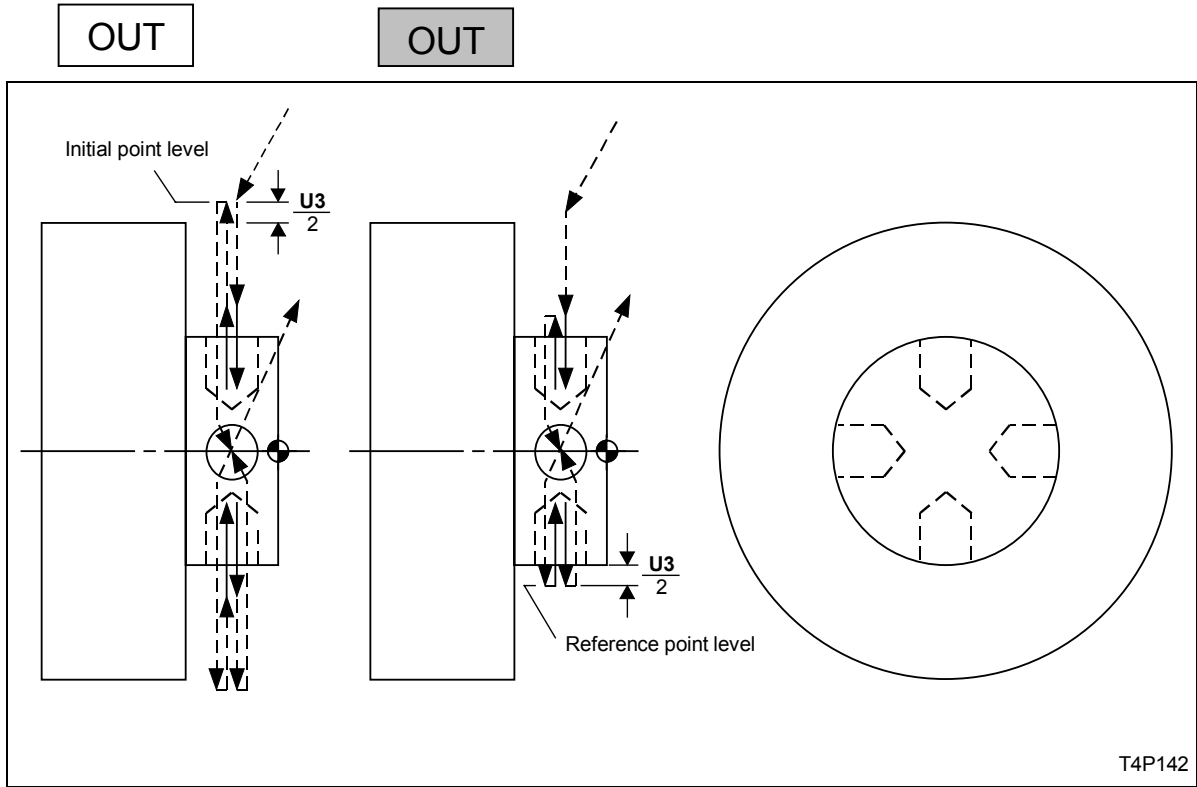
When creating a MDR/MTP process the menu options will ask you to select from the choices below (BAK, only on 2nd spindle machines).



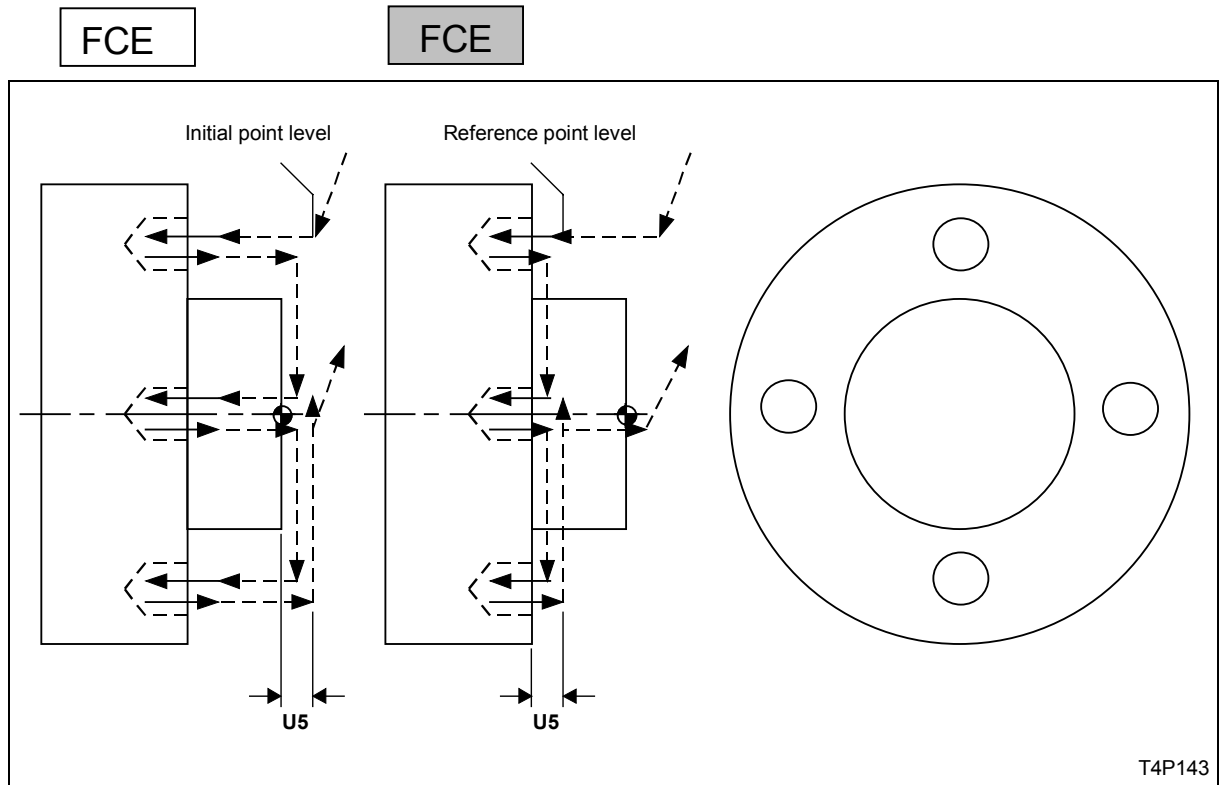
The choice between normal and highlighted options affect tool retraction between hole positions. See below:

- OUT** : Outer periphery (return to the initial point)
- OUT** : Outer periphery (return to the reference point)
- FCE** : Front face (return to the initial point)
- FCE** : Front face (return to the reference point)
- BAK** : Back face (return to the initial point)
- BAK** : Back face (return to the reference point)

MDR/MTP



MDR/MTP



NOTE:

The differences in action will occur between 'Return to the initial point' and 'Return to the reference point', only if multiple holes are machined during one unit.

If 'Return to the initial point' is selected, the tip of the tool will return to the initial point (position that is away from the maximum-outside-diameter part or edge of the workpiece by the safety profile clearance amount) each time a hole is machined.

If 'Return to the reference point' is selected, the tip of the tool will return to the reference point (position at which the tool is away from the programmed starting point by the safety profile clearance amount) after machining of the first hole, and then start machining the next hole.

Before selecting 'Return to the reference point', check that during movement to the following hole positions, the tool tip will not interfere with any protruding sections of the workpiece or with any other

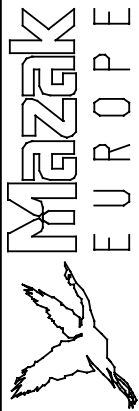




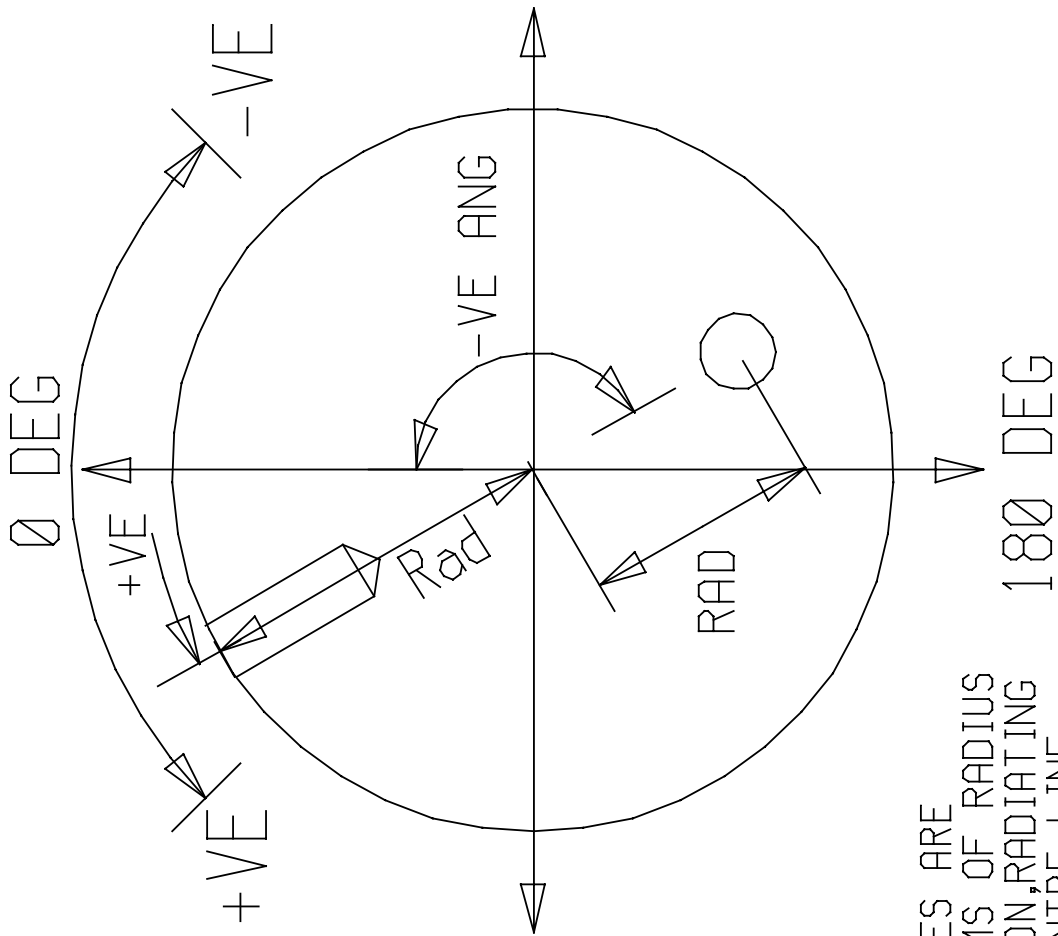
POLAR CO-ORDINATE SYSTEM



MAZATROL FUSION 640T



TITLE: POLAR CO-ORDS



POLAR CO-ORDINATES ARE SPECIFIED IN TERMS OF RADIUS & ANGULAR POSITION, RADIATING FROM MACHINE CENTRE LINE.

DRAWN BY: PW
 DRG. No.: DATE: 12/98
 MATERIAL:

Setting sequence data

UNo.	UNIT	#	DIA	DEPTH	DEP-1	DEP-2	DEP-3	C-SD	FEED	TOOL
*	MDR ***	*	***	***	***	***	***	***	***	***
SEQ	SHP	SPT-R/x	SPT-TH/y	SPT-Z	NUM.	ANGLE	TYPE			
1	①	②	③	④	⑤	⑥	⑦			

①SHP

The following menu will be displayed when the cursor is placed at this item.

POINT		CIRCLE						SHAPE END
-------	--	--------	--	--	--	--	--	--------------

(a)

(b)

Select (a) or (b) from the menu above.

The data of the displayed menu represent hole-drilling position patterns.

- Select **POINT** if one hole is to be drilled at any position.
- Select **CIRCLE** to drill multiple holes at an equal pitch along the same circumference with its center set at the program origin.

② SPT-R/x, ③ SPT-TH/y ④ SPT-Z

Specify a drilling start position for the hole you are going to make.

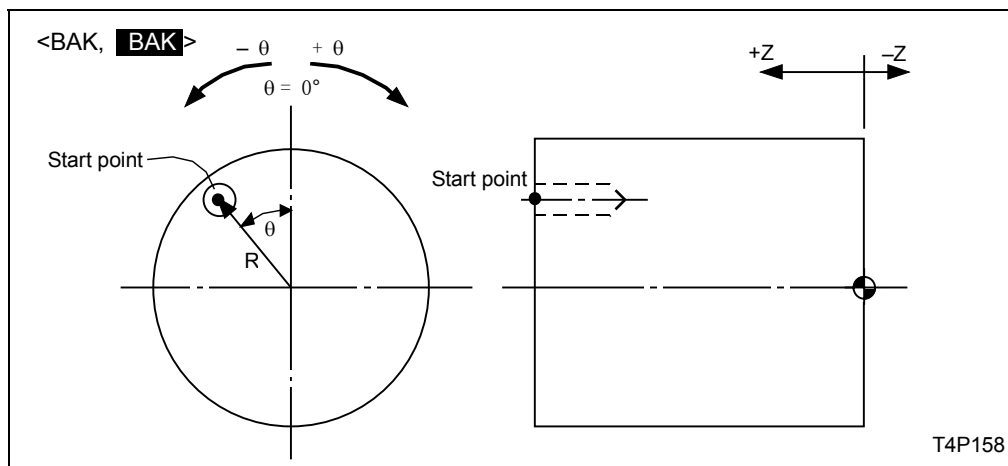
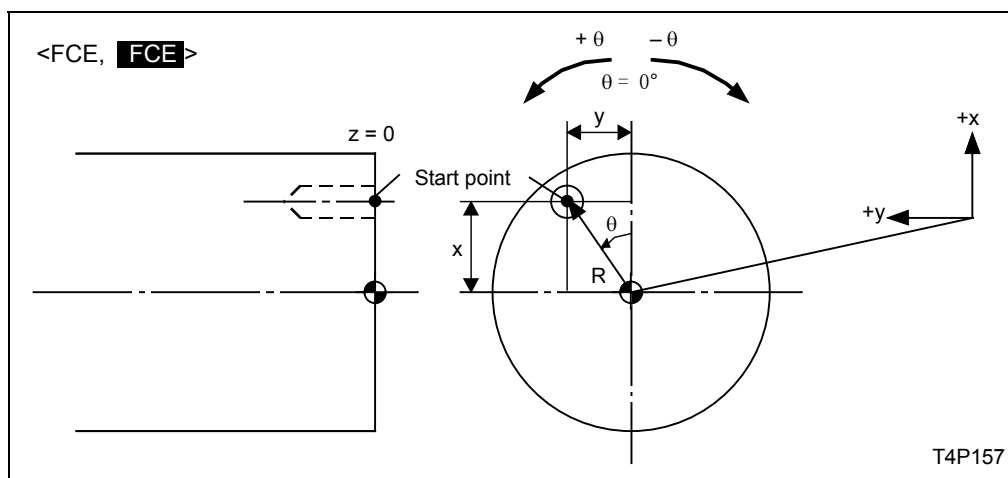
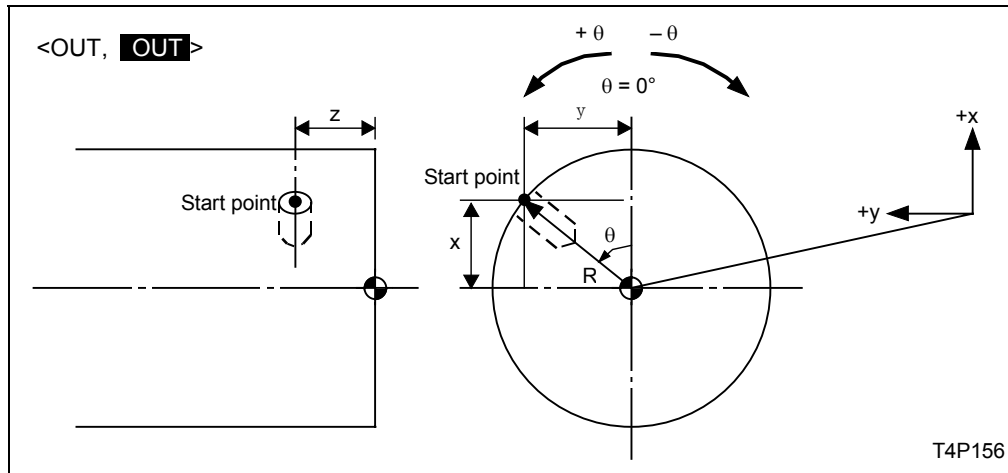
Set either the R- θ coordinates or x-y coordinates of the starting point in items ② and ③.

- To use the R- θ coordinates, set the radius and the angle as they are.
- To use the x-y coordinates, set data after reversing **x-y INPUT** display by pressing its menu key.

Set the Z-coordinate of the starting point in data filed ④.

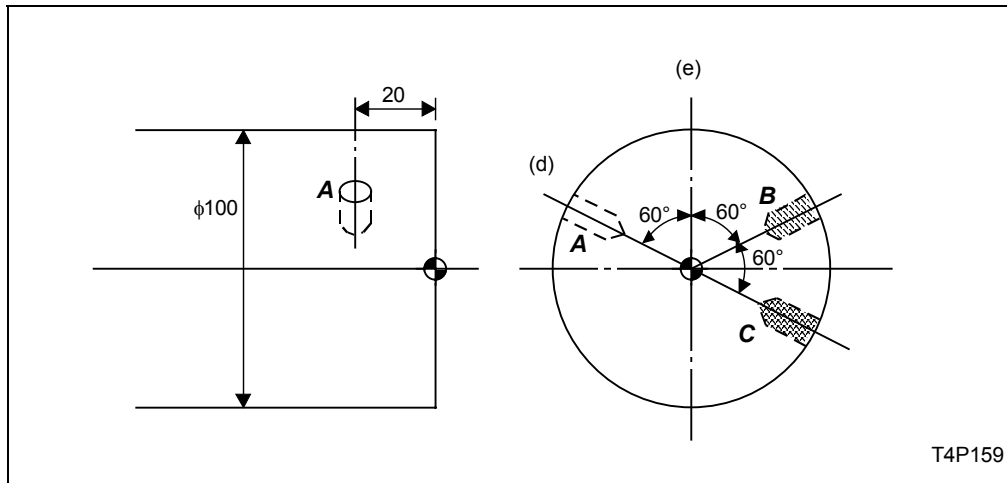
Note 1: For **BAK** and **BAK** only R- θ coordinates can be entered (a restriction because of the 1-degree orientation function of the No. 2 spindle).

Note 2: The manner of assigning a sign for θ is opposite between BAK and OUT or FCE.



Note 3: The C-axis program origin position ($\theta = 0^\circ$) can be taken at any point convenient for programming.

Example: To drill holes *A*, *B* and *C* at the positions shown below.



1) Set the following data if you have taken the position of (d) as $\theta = 0^\circ$:

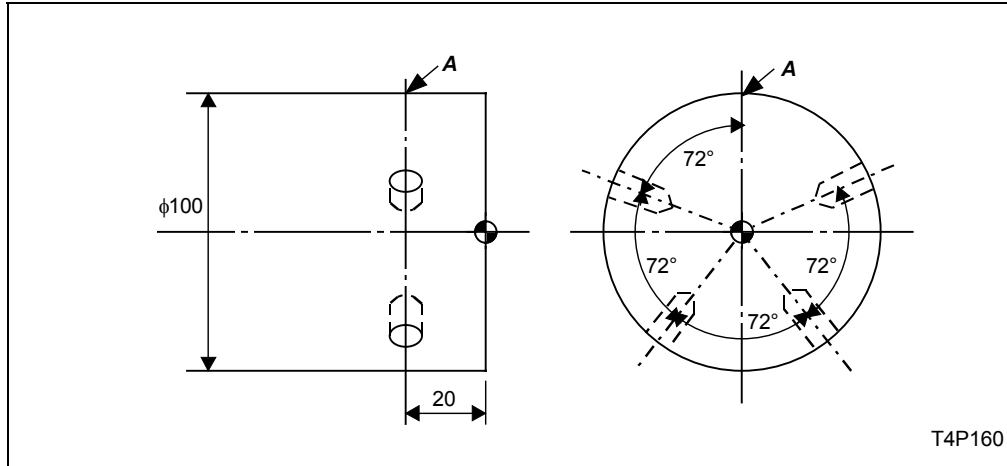
UNo.	UNIT	#	DIA	DEPTH	DEP-1
*	MDR OUT	*	***	***	***
SEQ	SHP	SPT-R/x	SPT-TH/y	SPT-Z	
Hole <i>A</i> →	1	PNT	50.	0.	20.
Hole <i>B</i> →	2	PNT	50.	-120.	20.
Hole <i>C</i> →	3	PNT	50.	-180.	20.

2) Set the following data if you have taken the position of (e) as $\theta = 0^\circ$:

UNo.	UNIT	#	DIA	DEPTH	DEP-1
*	MDR OUT	*	***	***	***
SEQ	SHP	SPT-R/x	SPT-TH/y	DEP-Z	
Hole <i>A</i> →	1	PNT	50.	60.	20.
Hole <i>B</i> →	2	PNT	50.	-60.	20.
Hole <i>C</i> →	3	PNT	50.	-120.	20.

Note 4: If you have selected **CIRCLE** for data item ①, you can set the starting point at a position other than the actual drilling position.

Example: To drill holes at the positions shown below:



Point *A* can be set as the starting point.

In this case, however, 1 (No machining at the starting position) must be set in data field ⑦, **TYPE**, described below.

UNo.	UNIT	#	DIA	DEPTH	DEP-1	DEP-2		
*	MDR OUT	*	***	***	***	***		
SEQ	SHP	SPT-R/x	SPT-TH/y	SPT-Z	NUM.	ANGLE	TYPE	
1	CRC	50.	0.	20.	4.	72.	<u>1</u>	

⑤ NUM.

- If **POINT** is selected for data item ①:

A **◆** mark will be displayed in this position to indicate that no data can be set.

- If **CIRCLE** is selected for data item ①:

Set the number of holes to be drilled.

⑥ ANGLE

- If **POINT** is selected for data item ①:

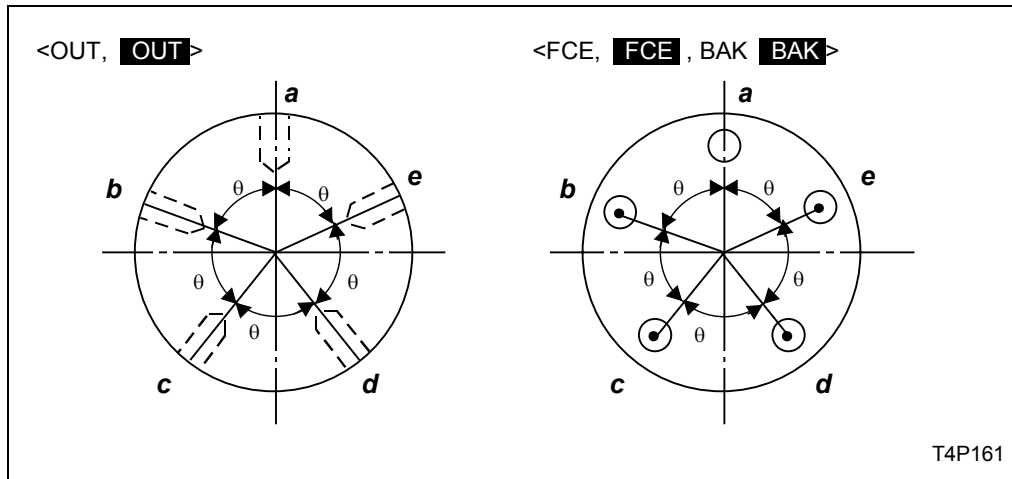
A **◆** mark will be displayed in this position to indicate that no data can be set.

- If **CIRCLE** is selected for data item ①:

Set a drilling pitch angle (θ in the diagram below) for the holes you are going to make.

If $\theta > 0$, the machining order is $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e$.

If $\theta < 0$, the machining order is $a \rightarrow e \rightarrow d \rightarrow c \rightarrow b$.



⑦ TYPE

- If **POINT** is selected for data item ①:

A **◆** mark will be displayed in this position to indicate that no data can be set.

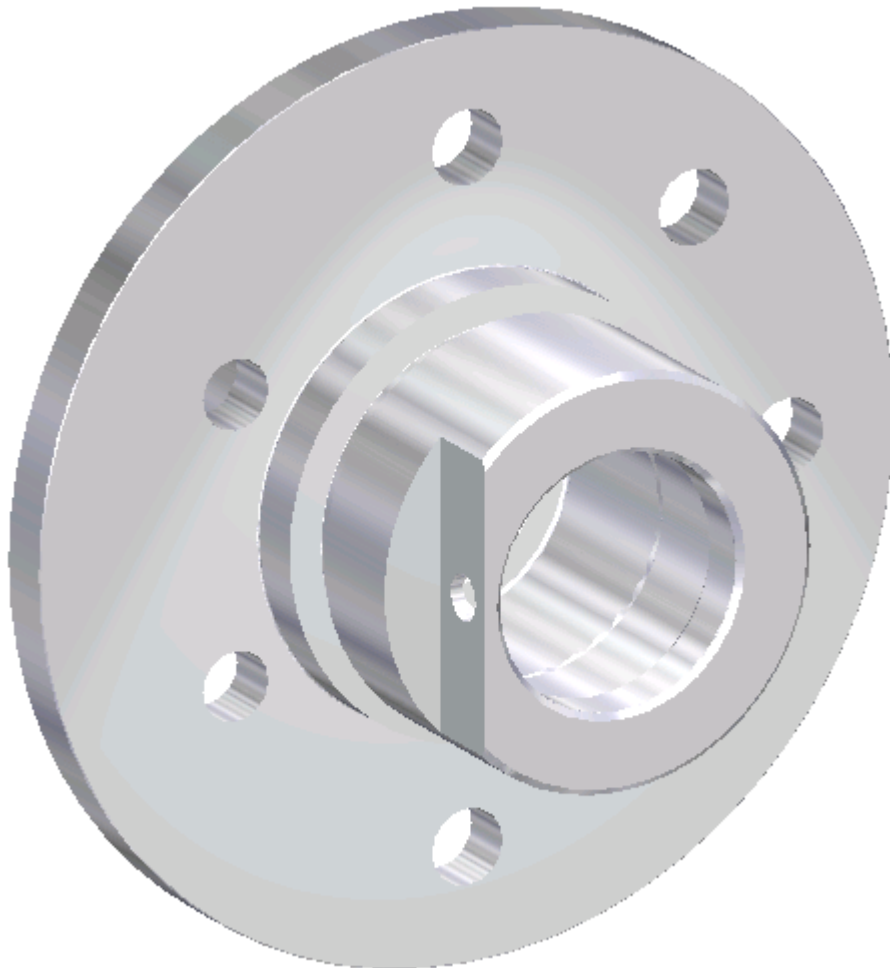
- If **CIRCLE** is selected for data item ①:

Specify whether the hole is to be drilled at the starting position whose data has been specified in data items ② to ④.

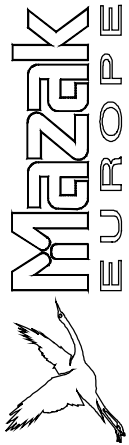
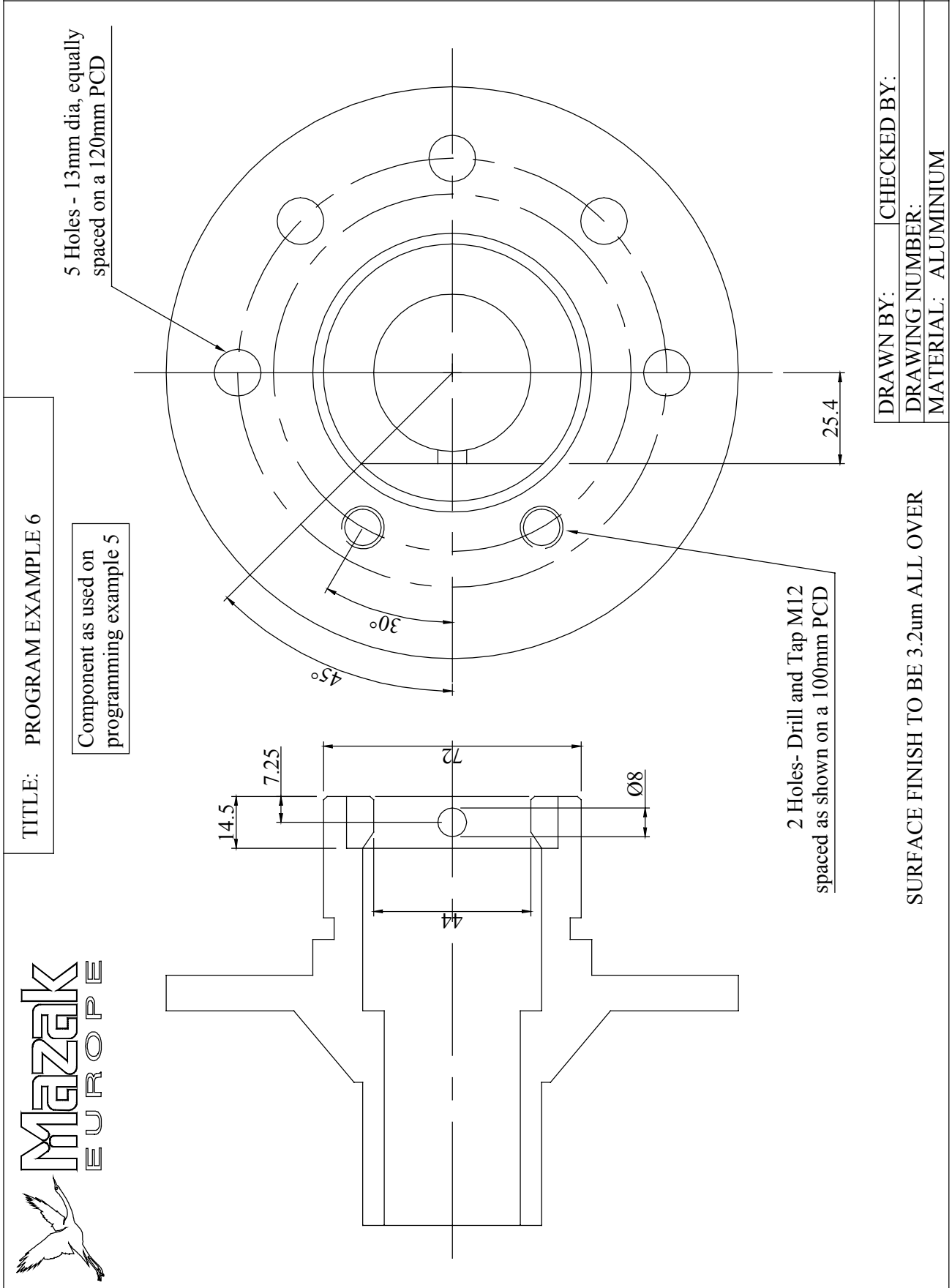
Set 0 if drilling is to be done.

Set 1 if drilling is not to be done.

PROGRAMMING EXAMPLE NO.6

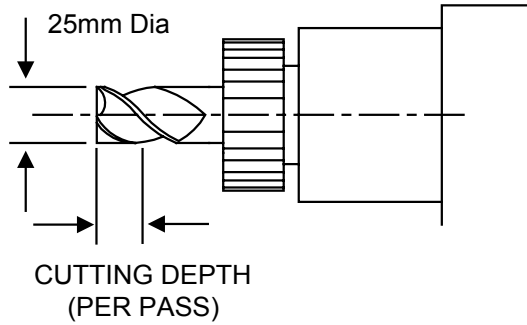




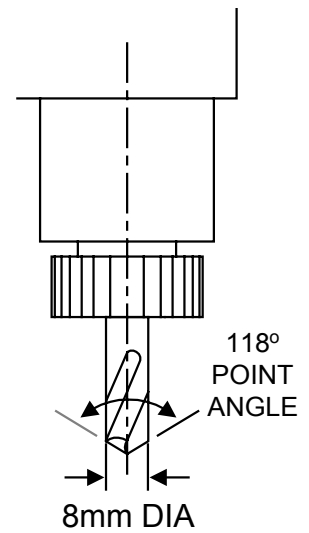


MILLING TOOLS FOR PROGRAM EXAMPLE No 6

EML EDG
(END MILL)

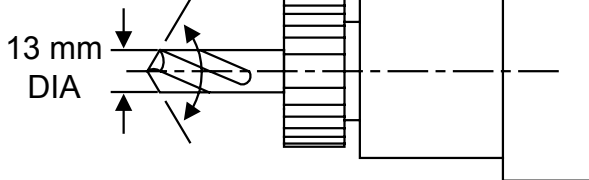


MDR OUT
(MILL DRILL)



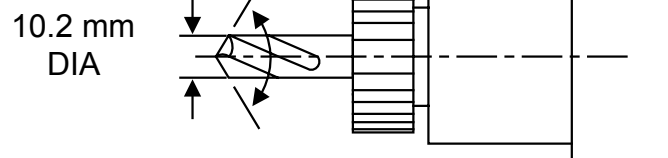
118°
POINT
ANGLE

MDR EDG
(MILL DRILL)

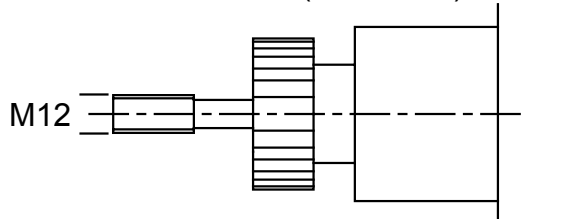


118°
POINT
ANGLE

MDR EDG
(MILL DRILL)



MTP EDG
(MILL TAP)





MAZATROL FUSION 640T

UNo. MAT OD-MAX ID-MIN LENGTH RPM FIN-X FIN-Z WORK FACE
 0 AL 160. 38. 120. 3000 0.4 0.1 0.

UNo. MODE
 1MTR OUT

SEQ SHP	SPT-X	SPT-Z	FPT-X	FPT-Z	RADIUS
1LIN	*	*	83.	48.	*
2LIN	*	*	160.	80.	*
3LIN	*	*	50.	120.	*

UNo. MODE # 1 # 2 # 3 # 4 # 5 # 6 # 7 # 8 # 9 #10 #11 #12
 2M 8

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
3BAR FCE 0	160.	48.	375	700	0.4	1.	3	
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN	*	*	83.	50.		*		

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
4BAR OUT 0	83.	0.	375	700	0.4	5.5	3	
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN C 1.	*	*	72.	40.		*		
2LIN	*	*	78.	50.		*		

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
5BAR OUT 0	160.	0.	375	700	0.4	5.5		2
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN C 1.	*	*	72.	40.		*	Rgh 4	
2LIN	*	*	78.	50.		*	Rgh 4	
3LIN C 0.5	*	*	160.	50.5		*	Rgh 4	

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
+ 6BAR BAK 0	160.	80.	375	700	0.35	3.	4A	4A
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN	*	*	88.564	60.		*	Rgh 4	
2TPR	88.564	60.	55.	80.		50.	Rgh 4	

UNo. MODE # No.	PITCH	WIDTH	FINISH	RV	FV	FEED	DEP.	R-TOOL	F-TOOL
7GRV OUT 1 1		6.	0.	120	139	0.1	2.	8	8
SEQ S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR	ANGLE	ROUGH		
1	72.	34.	66.	34.			Rgh 4		

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
8BAR IN 0	38.	0.	375	700	0.4	5.	6	7
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN C 1.5	*	*	44.	10.		*	Rgh 4	
2TPR	44.	10.	50.	14.5		-33.69	Rgh 4	
3LIN	*	*	50.	60.		*	Rgh 4	
4LIN C 0.5	*	*	38.	60.5		*	Rgh 4	

UNo. MODE GRV-WID	DEPTH	FIN-1	FIN-2	RV	FV	R-FR 1	R-FR 2	R-TOOL	F-TOOL
9LFT FCE 25.	14.5	0.	0.	150	300	0.15	0.25	10A	10A
SEQ SHP	FPT-R/x	FPT-An/y	FPT-Z	F-CNR	RADIUS	ROUGH			
1STP	36.	135.	0.		*	Rgh 4			
2LIN	36.	45.	*		*	Rgh 4			

UNo. MODE #	DIA.	DEPTH	DEP-1	DEP-2	DEP-3	V	FEED	TOOL
10MDR OUT 2	8.	15.	8.	3.	3.	25	0.032	10C
SEQ SHP	SPT-R/x	SPT-An/y	SPT-Z	NUM.	ANGLE	TYPE		
1PNT	25.4	90.	7.25	*	*	*		



MAZATROL FUSION 640T

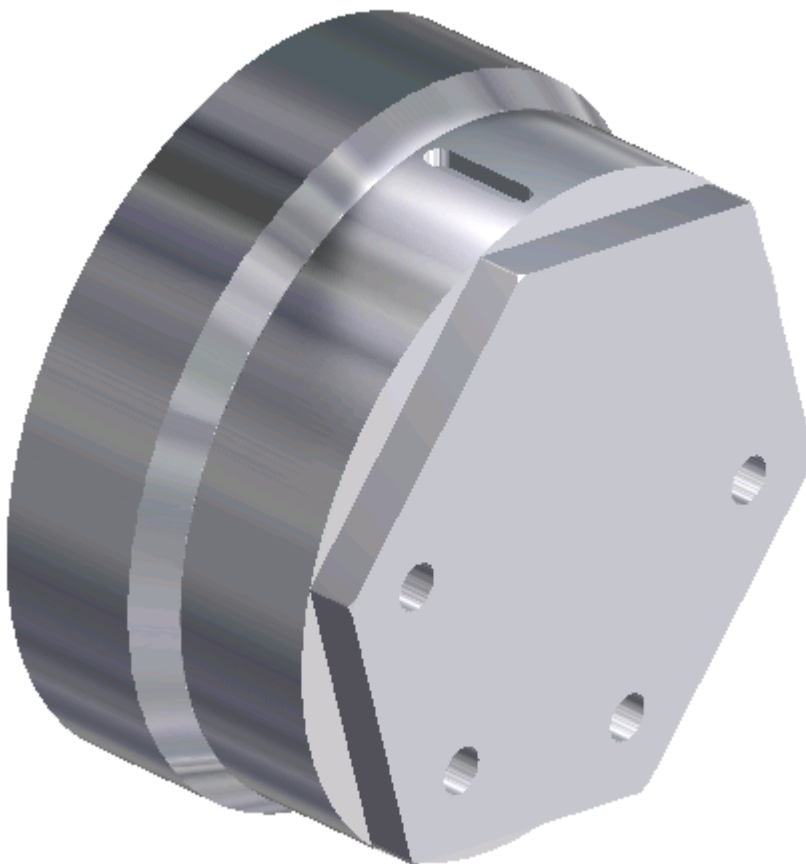
UNo.	MODE	#	DIA.	DEPTH	DEP-1	DEP-2	DEP-3	V	FEED	TOOL
11MDR	FCE	2	13.	15.	13.	3.	3.	25	0.200	11A
SEQ	SHP	SPT-R/x	SPT-An/y	SPT-Z				NUM.	ANGLE	TYPE
1CIR		60.	0.	50.				5	-45.	0

UNo.	MODE	#	DIA.	DEPTH	DEP-1	DEP-2	DEP-3	V	FEED	TOOL
12MDR	FCE	2	10.2	15.	10.2	3.	3.	25	0.200	10D
SEQ	SHP	SPT-R/x	SPT-An/y	SPT-Z				NUM.	ANGLE	TYPE
1PNT		50.	60.	50.				*	*	*
2PNT		50.	120.	50.				*	*	*

UNo.	MODE	NOM-DIA	PITCH	DEPTH	DWELL	V	TOOL			
13MTP	FCE	M12.	1.75	15.	0.	8	9C			
SEQ	SHP	SPT-R/x	SPT-An/y	SPT-Z				NUM.	ANGLE	TYPE
1CIR		50.	60.	50.				2	60.	0

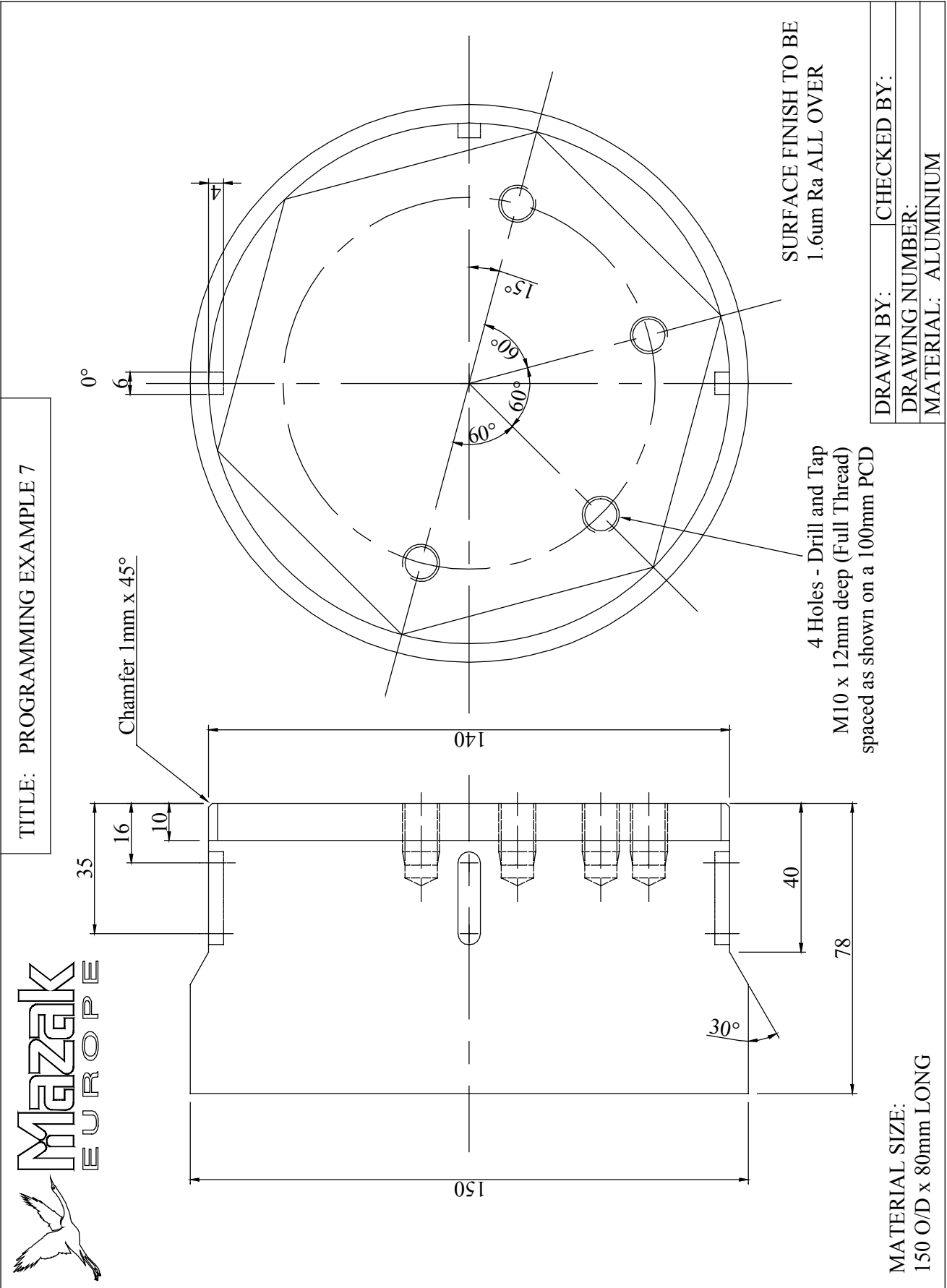
UNo.	MODE	COUNTER	RETURN	WK.No.	CONT.	NUM.	SHIFT
14END		0	0		0	0	0.

PROGRAMMING EXAMPLE N0.7

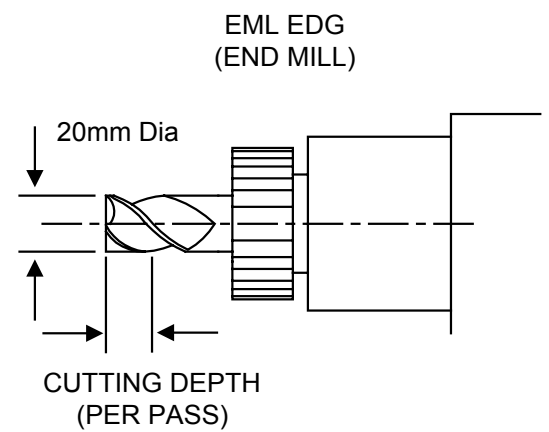
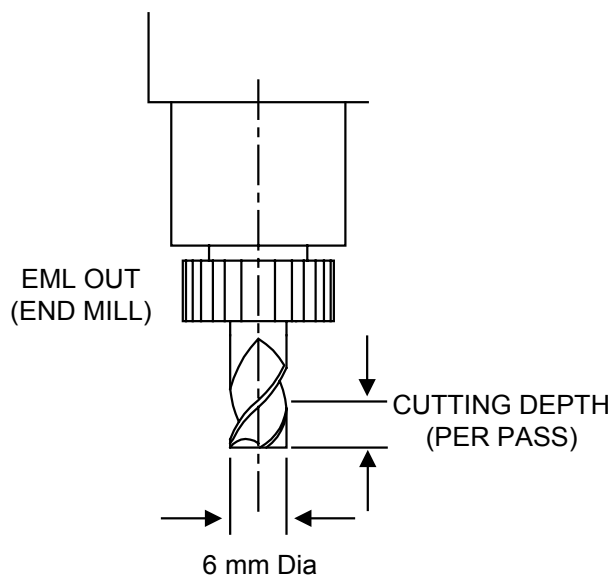
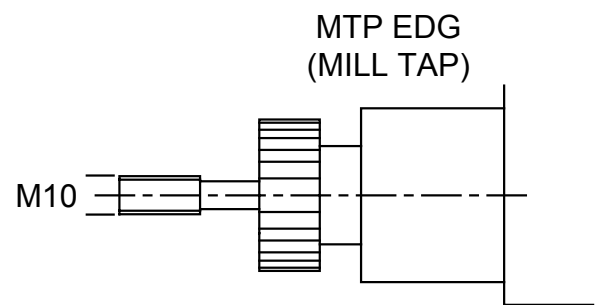
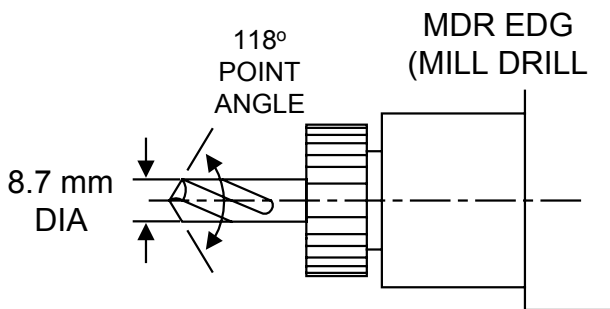
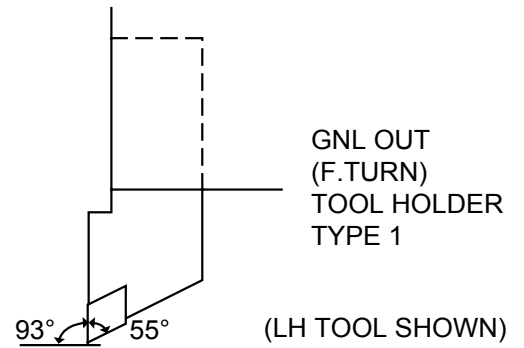
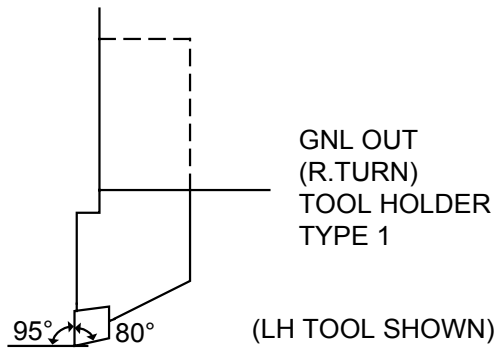




MAZATROL FUSION 640T



TOOLS FOR PROGRAM EXAMPLE No 7





MAZATROL FUSION 640T

```

UNo. MAT   OD-MAX  ID-MIN  LENGTH  RPM  FIN-X  FIN-Z  WORK FACE
0 AL      150.    0.     80.    3000  0.4    0.1    2.

UNo. MODE  # 1  # 2  # 3  # 4  # 5  # 6  # 7  # 8  # 9  #10  #11  #12
1M         8

UNo. MODE                RV    FV  R-FEED  R-DEP.  R-TOOL  F-TOOL
2EDG FCE                375   700  0.35   3.      1       2
SEQ          SPT-X      SPT-Z    FPT-X    FPT-Z                ROUGH
1            150.      2.      0.      0.                Rgh 5

UNo. MODE  #  CPT-X  CPT-Z                RV    FV  R-FEED  R-DEP.  R-TOOL  F-TOOL
3BAR OUT 0  150.    0.                375   700  0.4    5.5     1       2
SEQ SHP S-CNR  SPT-X    SPT-Z    FPT-X    FPT-Z    F-CNR/$  RADIUS/Ø  ROUGH
1LIN C 1.    *        *        140.    40.                *       Rgh 5
2TPR        140.    40.    150.    48.66                30.     Rgh 5

UNo. MODE  #  DIA.    DEPTH  DEP-1  DEP-2  DEP-3  V    FEED                TOOL
4MDR FCE 1  8.7    20.    8.7    3.     3.    62  0.034                11A
SEQ SHP  SPT-R/x  SPT-An/y  SPT-Z    SPT-Y/C  CTR1/PITCH  CTR2    NUM.  ANGLE  TYPE
1CIR   50.     75.     0.      *        *          *      4    60.    0

UNo. MODE  NOM-DIA  PITCH    DEPTH  DWELL  V                TOOL
5MTP FCE  M10.    1.5     12.    0.     20                11A
SEQ SHP  SPT-R/x  SPT-An/y  SPT-Z    SPT-Y/C  CTR1/PITCH  CTR2    NUM.  ANGLE  TYPE
1CIR   50.    -105.    0.      *        *          *      4    -60.    0

UNo. MODE  #  GRV-WID  DEPTH  FINISH  RV    FV  R-FR 1  R-FR 2  R-TOOL  F-TOOL
6MGV OUT 1  6.     4.     0.1    76    76  0.04  0.02  12A    12A
SEQ          SPT-R      SPT-An    SPT-Z  SPT-Y          FPT-R      FPT-Z    ROUGH
1            70.      0.        16.    0.            *          35.     Rgh 5
2            70.     -90.     16.    0.            *          35.     Rgh 5
3            70.    -180.    16.    0.            *          35.     Rgh 5

UNo. MODE  GRV-WID  DEPTH  FIN-1  FIN-2  RV    FV  R-FR 1  R-FR 2  R-TOOL  F-TOOL
7LFT FCE 20.    10.    0.1    0.1    83    101  0.1    0.05  9A     9A
SEQ SHP  FPT-R/x  FPT-An/y  FPT-Z    FPT-Y/C  F-CNR    RADIUS  ROUGH
1STP    70.    -105.    0.      *        *          *       Rgh 5
2LIN    70.    -165.    *        *        *          *       Rgh 5
3LIN    70.    -225.    *        *        *          *       Rgh 5
4LIN    70.    -285.    *        *        *          *       Rgh 5
5LIN    70.    -345.    *        *        *          *       Rgh 5
6LIN    70.    -45.     *        *        *          *       Rgh 5
7LIN    70.    -105.    *        *        *          *       Rgh 5

UNo. MODE  COUNTER  RETURN  WK.No.  CONT.  NUM.  SHIFT
8END      0         0       0       0       0     0.

```

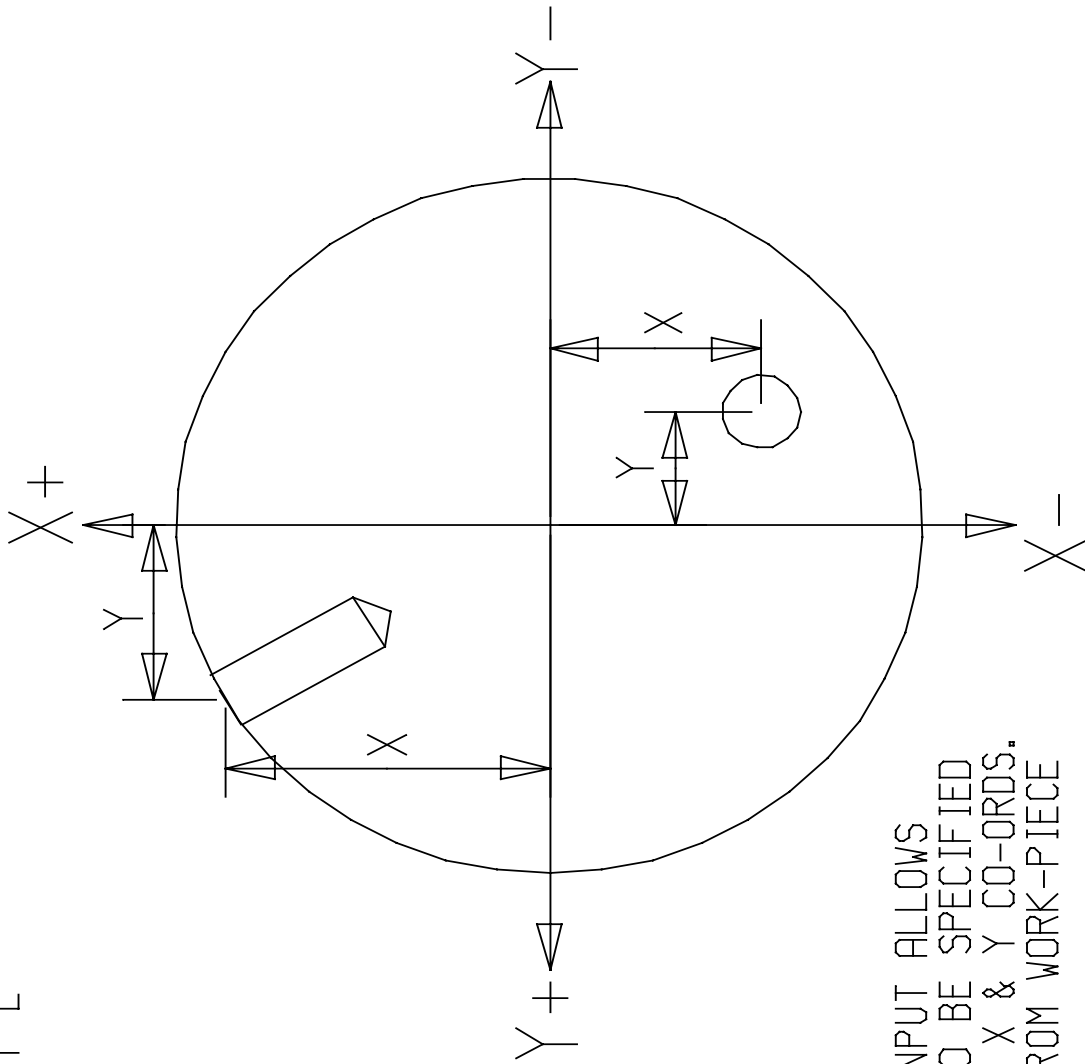
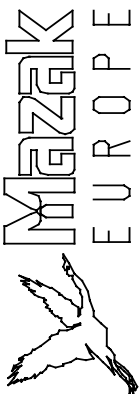




CARTESIAN CO-ORDINATE SYSTEM



TITLE: CARTESIAN CO-ORDS

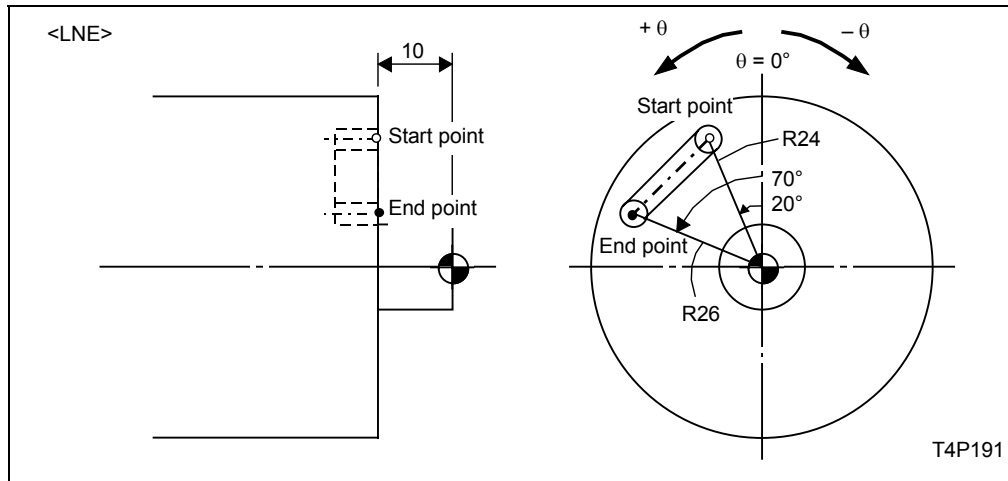


CARTESIAN INPUT ALLOWS
A POSITION TO BE SPECIFIED
IN TERMS OF X & Y CO-ORDS.
RADIATING FROM WORK-PIECE
CENTRE.

DRAWN BY: PW
DRG. No.: DATE: 12/98
MATERIAL:

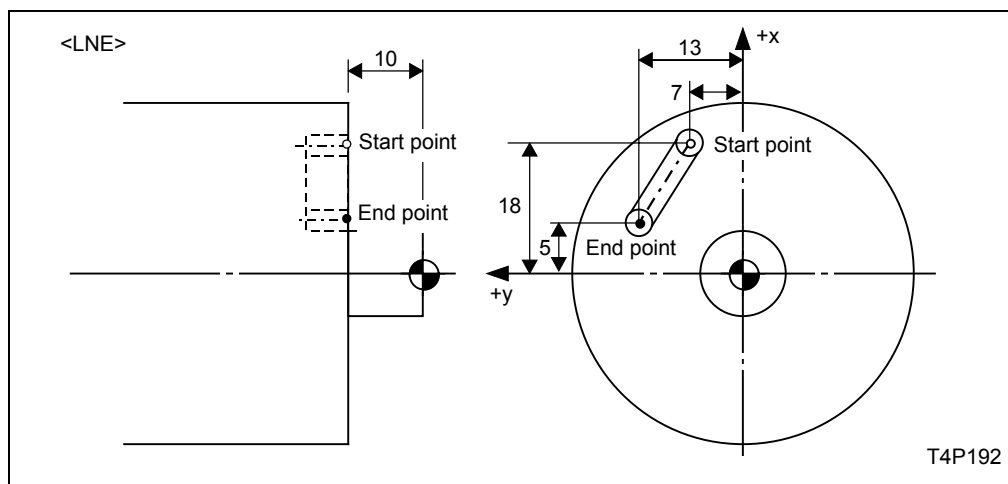
Examples using CARTESIAN co-ordinates in comparison to POLAR co-ordinates.

LINE



**R-θ-Z-
input**

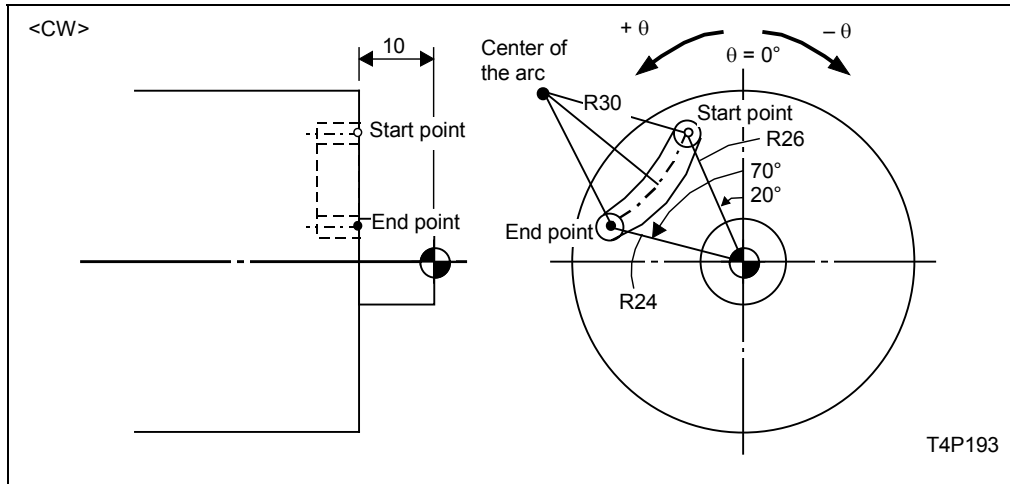
SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	24.	20.	10.	◆	◆	
2	LNE	26.	70.	◆		◆	



**x-y-Z-
input**

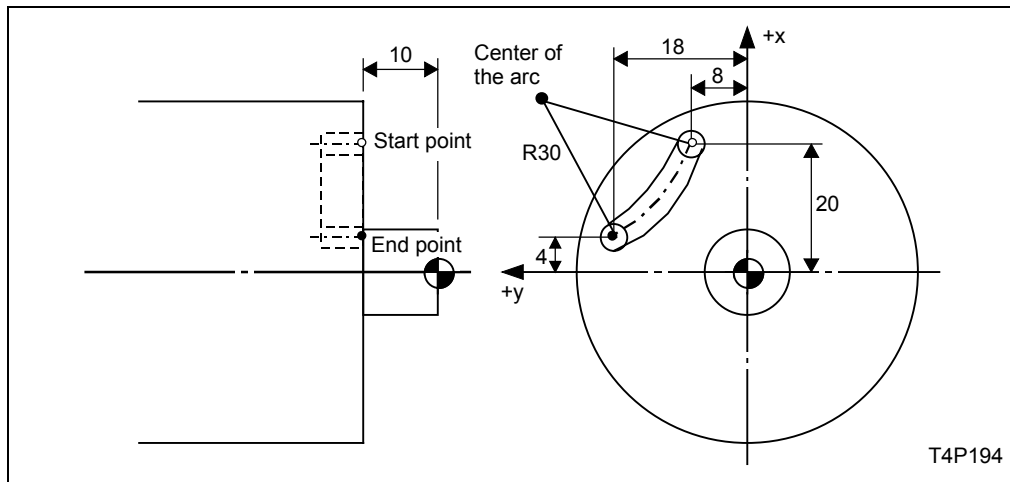
SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	18.	7.	10.	◆	◆	
2	LNE	5.	13.	◆		◆	

CW ARC



**R- θ -Z-
input**

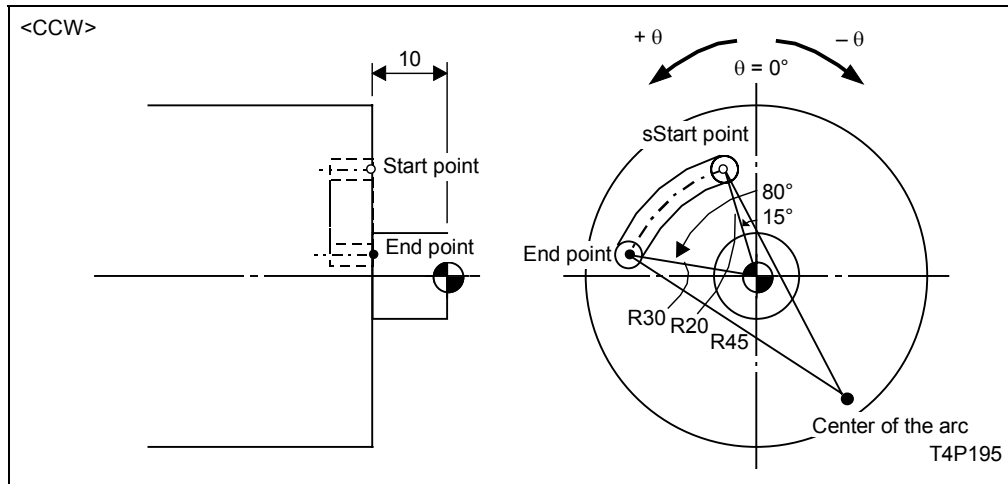
SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	26.	20.	10.	◆	◆	
2	CW	24.	70.	◆		30.	



**x-y-Z-
input**

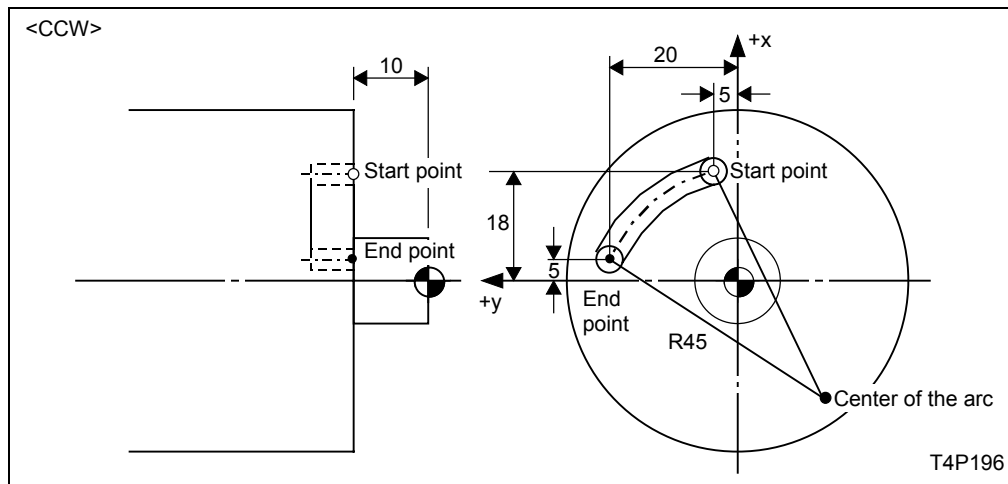
SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	20.	8.	10.	◆	◆	
2	CW	4.	18.	◆		30.	

CCW ARC



**R- θ -Z-
input**

SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	20.	15.	10.	◆	◆	
2	CCW	30.	80.	◆		45.	



**x-y-Z-
input**

SEQ	SHP	FPT-R/x	FPT-TH/y	FPT-Z	CNR	RADIUS	RGH
1	STP	18.	5.	10.	◆	◆	
2	CCW	5.	20.	◆		45.	

- Set data with a minus sign if the center angle of the arc is to exceed 180 degrees.

Example: If the machining into the pattern shown below is to be performed, set data shown below to one of the diagrams. (x-y-Z input)

UNIT	SPOR-BRD	DEPTH	FINISH
LCT	FCE	6		
SHP	FPT-R/x	FPT-TH/y	FPT-Z	... RADIUS
STP	15.	0.	0.	◆
CCW	0.	15.	◆	15.
				↓
				Plus value

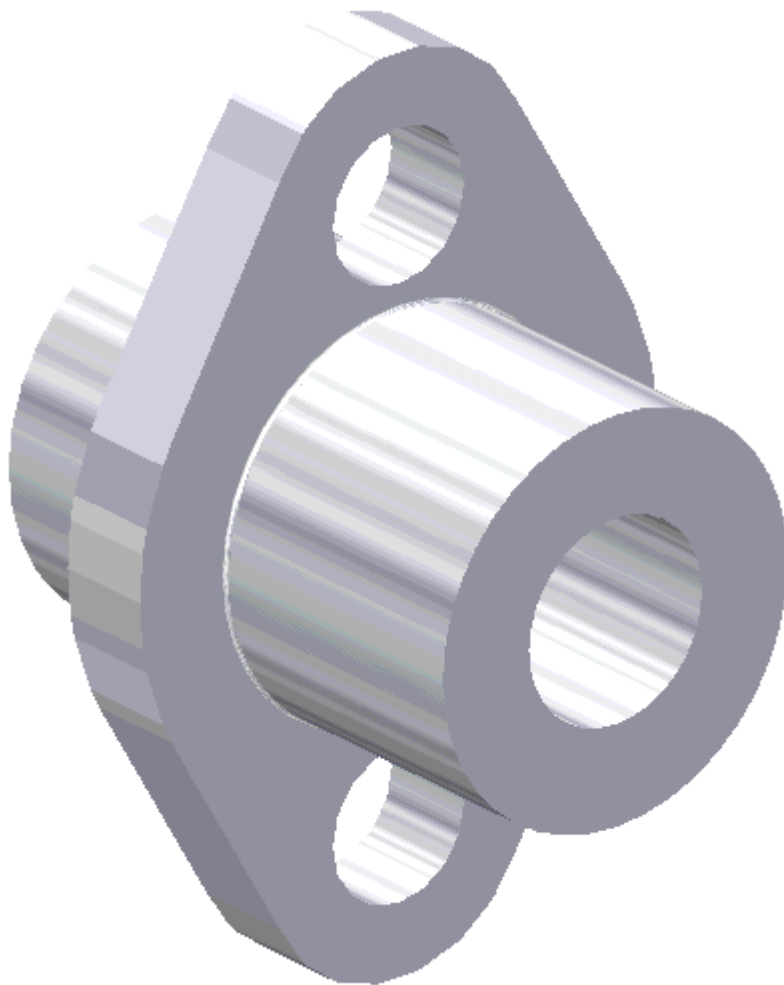
UNIT	SPOR-BRD	DEPTH	FINISH
LCT	FCE	6		
SHP	FPT-R/x	FPT-TH/y	FPT-Z	... RADIUS
STP	15.	0.	0.	◆
CCW	0.	15.	◆	-15.
				↓
				Minus value

T4P205

For arcs, the two patterns shown in the diagram above are usually recognized as machining patterns even if the start point, end point and radius are designated. Set radius data as a plus value if the center angle of the arc is larger than 0 degree but up to 180 degrees, or as a minus value if the center angle is larger than 180 degrees but up to 360 degrees. The statement made above also applies to mill-line right- and mill-line left-machining units.



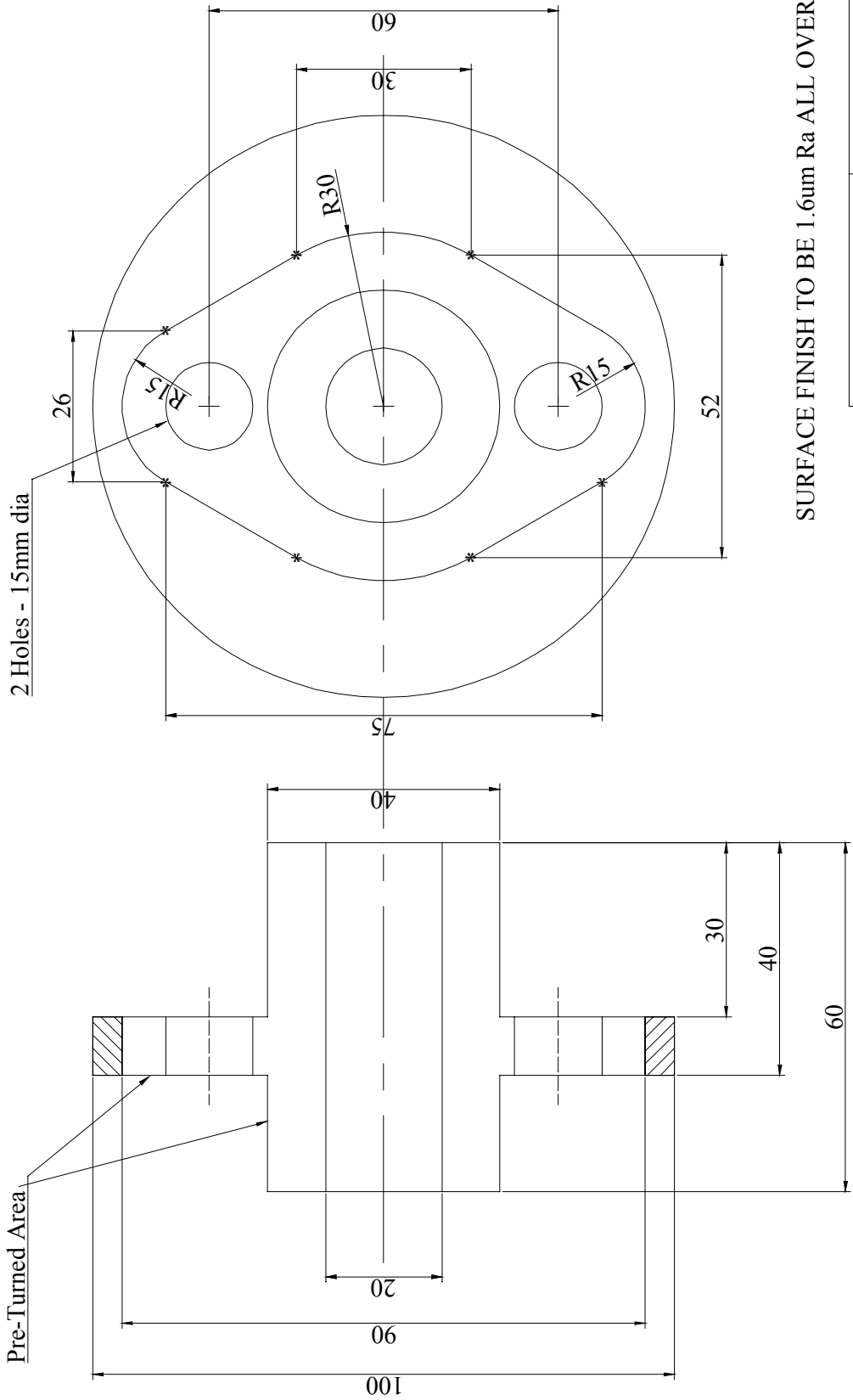
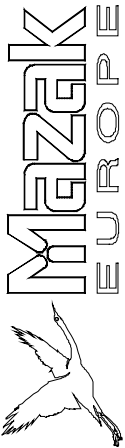
PROGRAMMING EXAMPLE No.8





MAZATROL FUSION 640T

TITLE: PROGRAMMING EXAMPLE 8

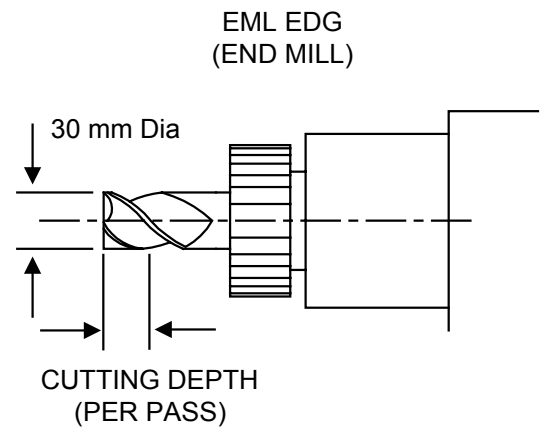
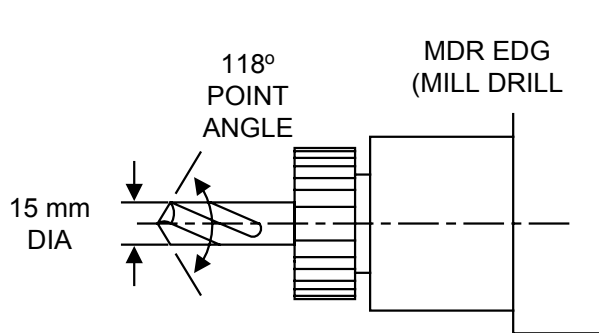
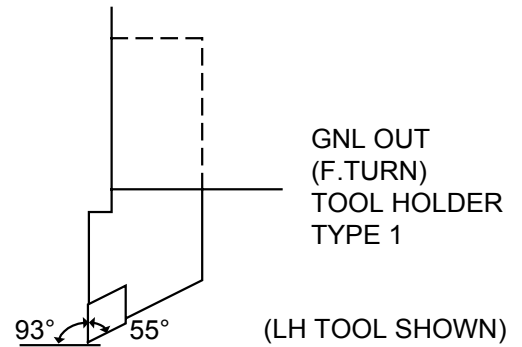
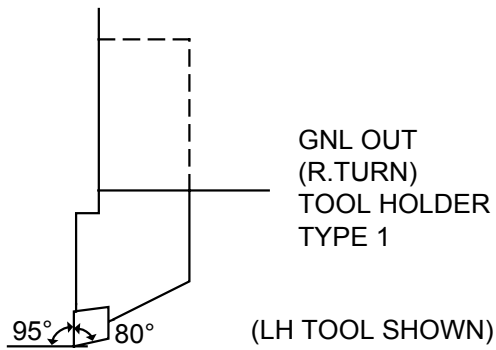


SURFACE FINISH TO BE 1.6um Ra ALL OVER

DRAWN BY:	CHECKED BY:
DRAWING NUMBER:	
MATERIAL:	ALUMINIUM

MATERIAL SIZE:
100 O/D x 20 I/D x 60 LONG

TOOLS FOR PROGRAM EXAMPLE No 8





MAZATROL FUSION 640T

UNo. MAT OD-MAX ID-MIN LENGTH RPM FIN-X FIN-Z WORK FACE
 0 S45C 100. 20. 60. 3000 0.4 0.1 0.

UNo. MODE
 1MTR OUT

SEQ SHP	SPT-X	SPT-Z	FPT-X	FPT-Z	RADIUS
1LIN	*	*	100.	40.	*
2LIN	*	*	40.	40.	*
3LIN	*	*	40.	60.	*

UNo. MODE # 1 # 2 # 3 # 4 # 5 # 6 # 7 # 8 # 9 #10 #11 #12
 2M 8

UNo. MODE #	CPT-X	CPT-Z	RV	FV	R-FEED	R-DEP.	R-TOOL	F-TOOL
3BAR OUT 0	100.	0.	375	468	0.4	5.5	1	2
SEQ SHP S-CNR	SPT-X	SPT-Z	FPT-X	FPT-Z	F-CNR/\$	RADIUS/ø	ROUGH	
1LIN	*	*	40.	30.	*	Rgh 5		
2LIN	*	*	92.	41.	*	Rgh 5		

UNo. MODE	GRV-WID	DEPTH	FIN-1	FIN-2	RV	FV	R-FR 1	R-FR 2	R-TOOL	F-TOOL
4LFT FCE	30.	11.	0.1	0.1	248	101	0.04	0.02	10A	10A
SEQ SHP	FPT-R/x	FPT-An/y	FPT-Z	F-CNR	RADIUS	ROUGH				
1STP	0.	-30.	30.	*	Rgh 5					
2CW	-15.	-26.	*	30.	Rgh 5					
3LIN	-37.5	-13.	*	*	Rgh 5					
4CW	-37.5	13.	*	15.	Rgh 5					
5LIN	-15.	26.	*	*	Rgh 5					
6CW	15.	26.	*	30.	Rgh 5					
7LIN	37.5	13.	*	*	Rgh 5					
8CW	37.5	-13.	*	15.	Rgh 5					
9LIN	15.	-26.	*	*	Rgh 5					
10CW	0.	-30.	*	30.	Rgh 5					

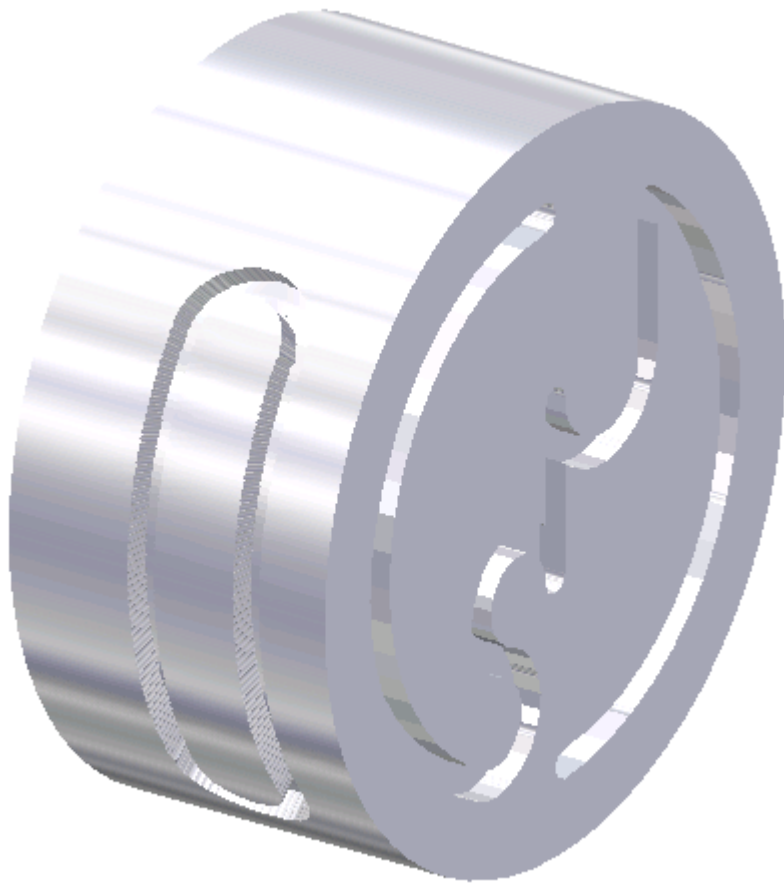
UNo. MODE #	DIA.	DEPTH	DEP-1	DEP-2	DEP-3	V	FEED	TOOL
5MDR FCE 0	15.	18.	9.	3.	3.	25	0.200	11A
SEQ SHP	SPT-R/x	SPT-An/y	SPT-Z	NUM.	ANGLE	TYPE		
1CIR	30.	0.	30.	2	180.	0		

UNo. MODE	COUNTER	RETURN	WK.No.	CONT.	NUM.	SHIFT
6END	1	0		0	0	0.



MAZATROL FUSION 640T

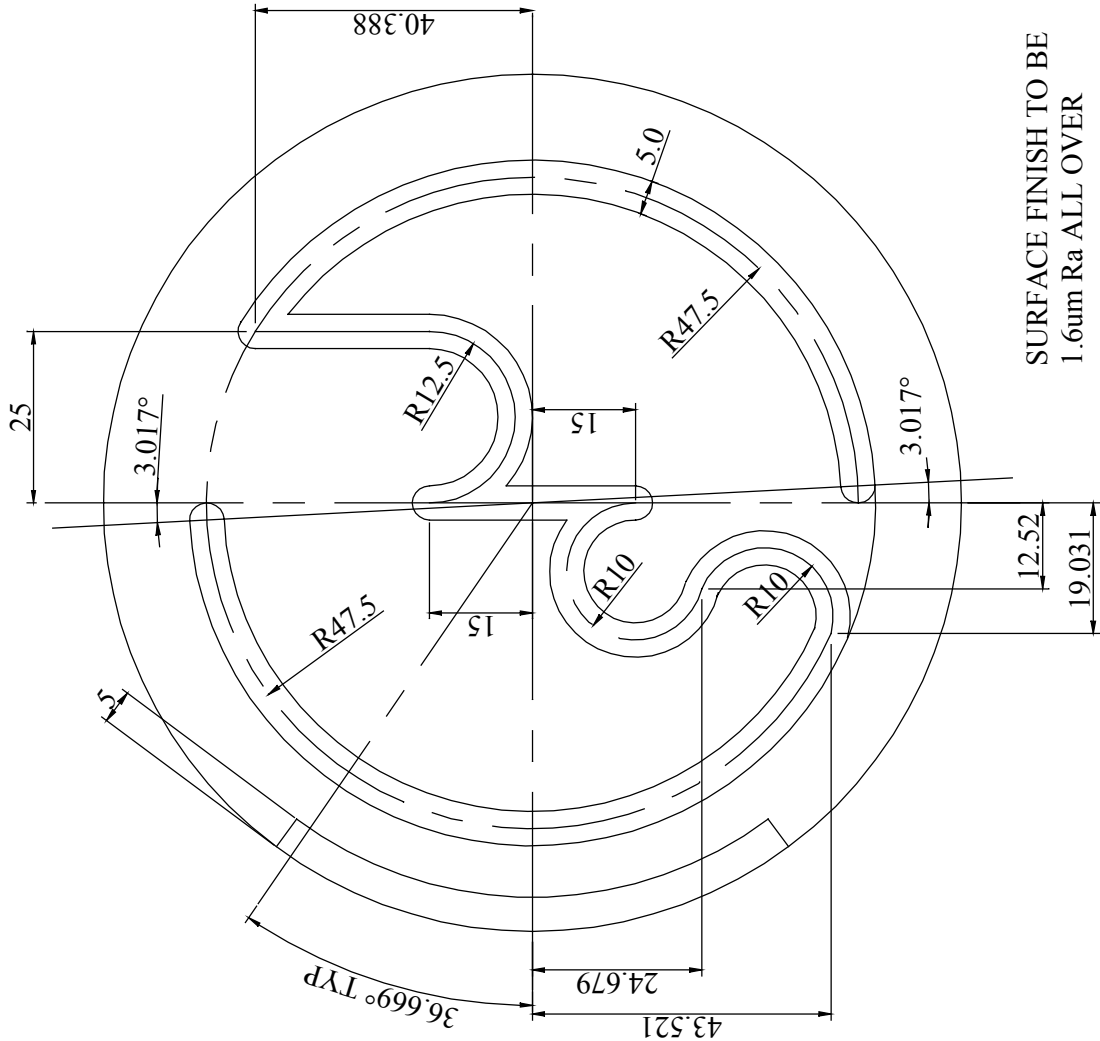
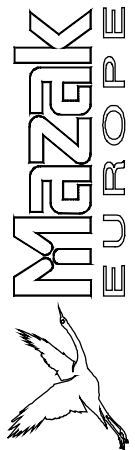
PROGRAMMING EXAMPLE NO.9





MAZATROL FUSION 640T

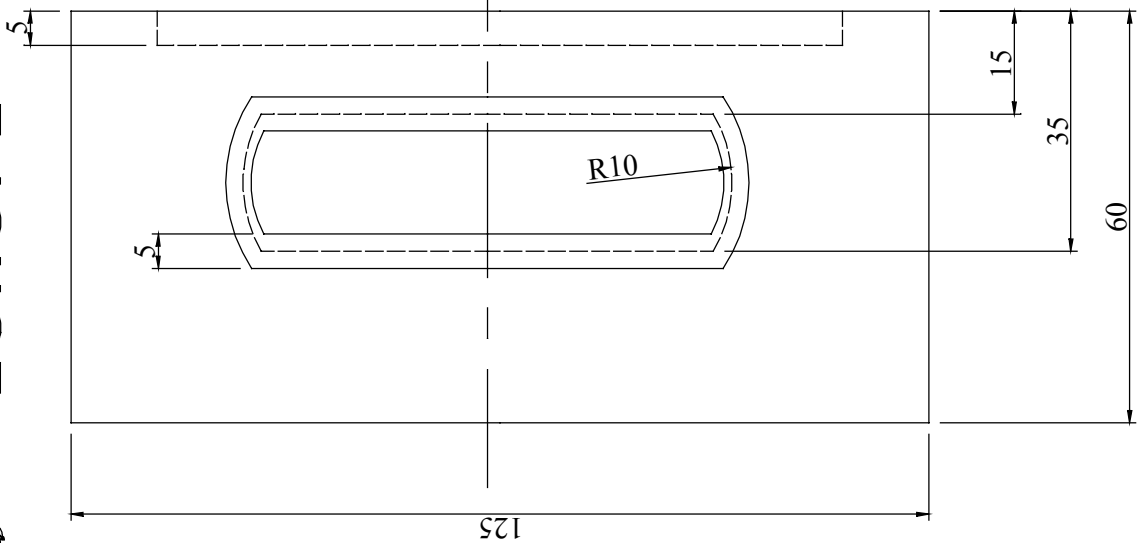
TITLE: PROGRAMMING EXAMPLE 9



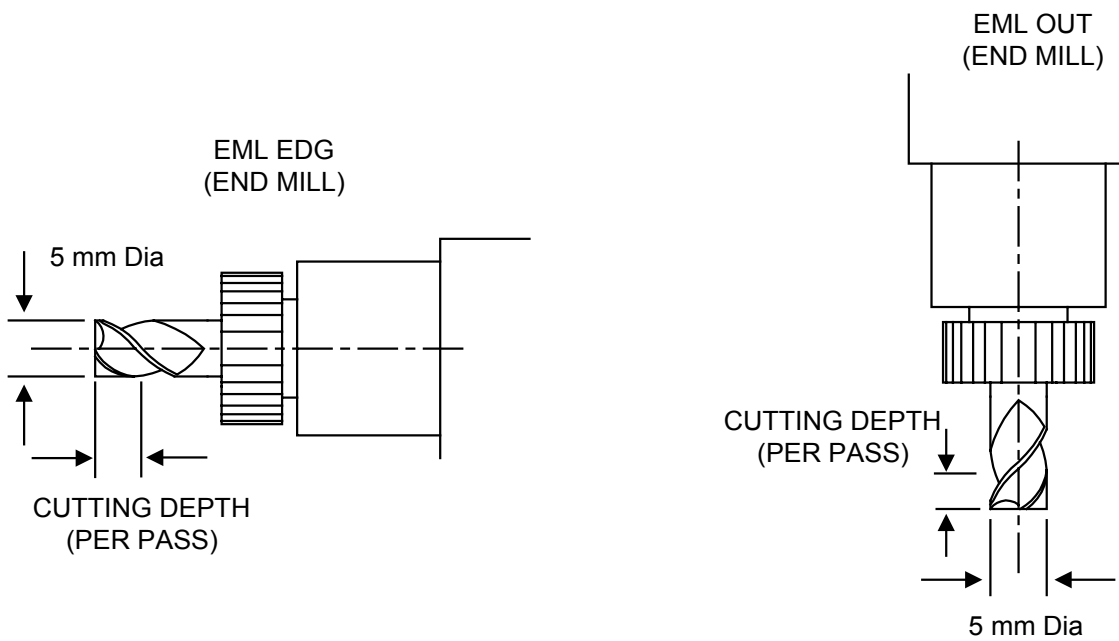
SURFACE FINISH TO BE
1.6um Ra ALL OVER

DRAWN BY: CHECKED BY:
DRAWING NUMBER:
MATERIAL: ALUMINIUM

MATERIAL SIZE:
125 O/D x 60mm LONG



TOOLS FOR PROGRAM EXAMPLE No 9





MAZATROL FUSION 640T

UNo.	MAT	OD-MAX	ID-MIN	LENGTH	RPM	FIN-X	FIN-Z	WORK FACE
0	AL	125.	0.	60.	3000	0.4	0.1	0.

UNo.	MODE	# 1	# 2	# 3	# 4	# 5	# 6	# 7	# 8	# 9	#10	#11	#12
1	M	8											

UNo.	MODE	GRV-WID	DEPTH	FINISH	RV	FV	R-FR 1	R-FR 2	R-TOOL	F-TOOL
2	LCT FCE	5.	5.	0.1	83	101	0.033	0.016	10B	10B
SEQ	SHP	FPT-R/x	FPT-An/y	FPT-Z			F-CNR	RADIUS	ROUGH	
1	STP	47.5	3.017	0.				*	Rgh 5	
2	CCW	-43.521	19.031	*				47.5	Rgh 5	
3	CCW	-24.679	12.52	*				10.	Rgh 5	
4	CW	-15.	0.	*				-10.	Rgh 5	
5	LIN	15.	0.	*				*	Rgh 5	
6	CCW	15.	-25.	*				12.5	Rgh 5	
7	LIN	40.388	-25.	*				*	Rgh 5	
8	CW	47.5	-176.983	*				47.5	Rgh 5	

UNo.	MODE	GRV-WID	DEPTH	FINISH	RV	FV	R-FR 1	R-FR 2	R-TOOL	F-TOOL
3	LCT OUT	5.	5.	0.1	83	101	0.033	0.016	7A	7A
SEQ	SHP	FPT-R/x	FPT-An/y	FPT-Z			F-CNR	RADIUS	ROUGH	
1	STP	62.5	90.	15.				*	Rgh 5	
2	LIN	*	53.331	15.				*	Rgh 5	
3	CCW	*	53.331	35.				10.	Rgh 5	
4	LIN	*	126.669	35.				*	Rgh 5	
5	CCW	*	126.669	15.				10.	Rgh 5	
6	LIN	*	90.	15.				*	Rgh 5	

UNo.	MODE	COUNTER	RETURN	WK.No.	CONT.	NUM.	SHIFT
4	END	1	0		0	0	0.



MAZATROL FUSION 640T